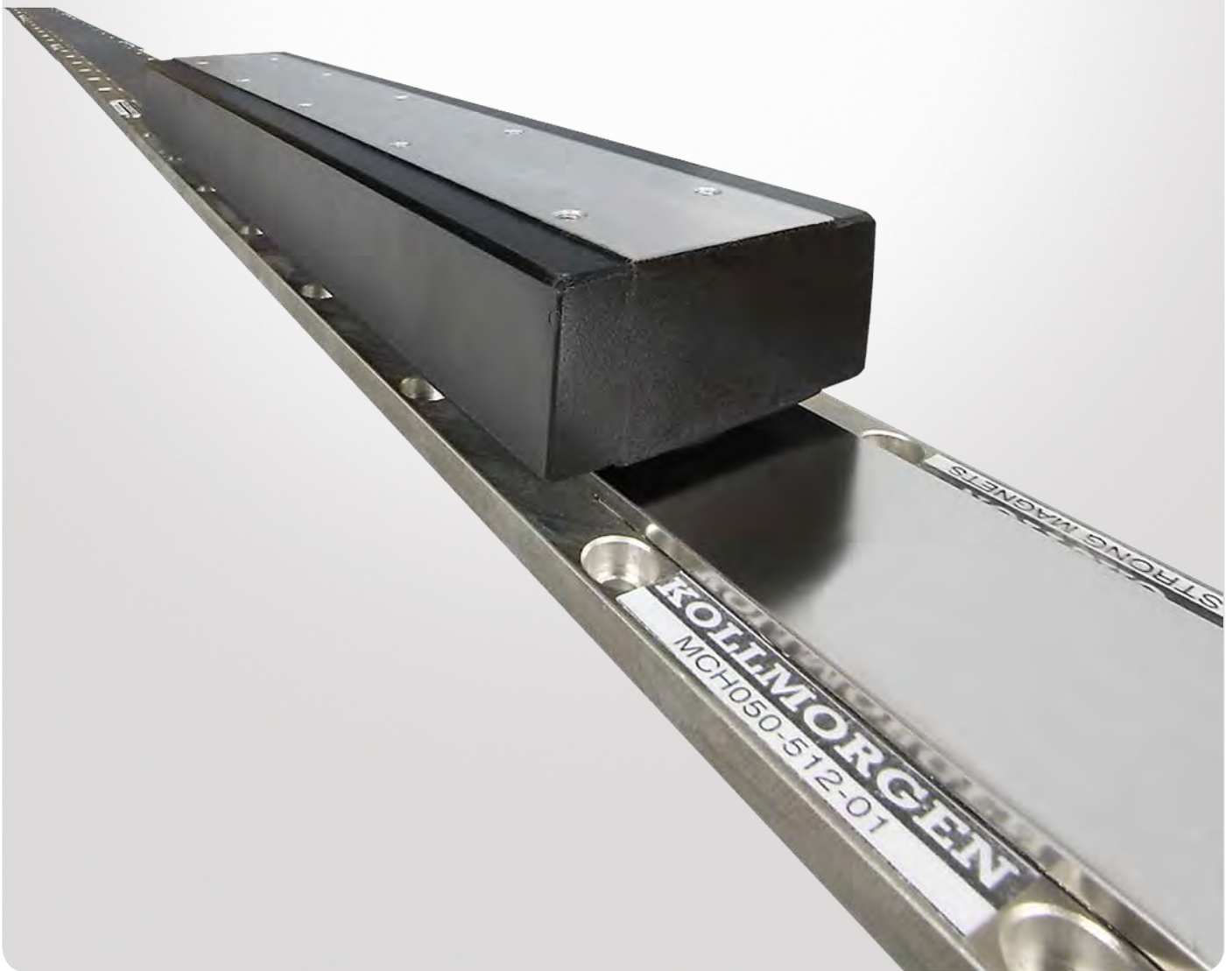


# Kollmorgen Direct Drive Linear Motor Selection Guide



**KOLLMORGEN**

*Because Motion Matters™*

# Kollmorgen.

## Every solution comes from a real understanding of OEM challenges facing machine designers and users.

**The ever-escalating demands of the marketplace mean increased pressure on machine designers and users at every turn.** Time constraints. Demands for better performance. Having to think about the next-generation machine even before the current one is built. While expectations are enormous, budgets are not. Kollmorgen's innovative automation and motion solutions and broad range of quality products help engineers not only overcome these challenges but also build truly differentiated machines.

**Because motion matters, it's our focus.** Motion can distinctly differentiate a machine and deliver a marketplace advantage by improving its performance. This translates to overall increased efficiency on the factory floor. Perfectly deployed machine motion can make your customer's machine more reliable and efficient, enhance accuracy and improve operator safety. Motion also represents endless possibilities for innovation. We've always understood this potential, and thus, have kept motion at our core, relentlessly developing products that offer precision control of speed, accuracy and position in machines that rely on complex motion.

**Removing the Barriers of Design, Sourcing, and Time**

At Kollmorgen, we know that OEM engineers can achieve a lot more when obstacles aren't in the way. So, we knock them down in three important ways:

**Integrating Standard and Custom Products**

The optimal solution is often not clear-cut. Our application expertise allows us to modify standard products or develop totally custom solutions across our whole product portfolio so that designs can take flight.

**Providing Motion Solutions, Not Just Components**

As companies reduce their supplier base and have less engineering manpower, they need a total system supplier with a wide range of integrated solutions. Kollmorgen is in full response mode with complete solutions that combine programming software, engineering services and best-in-class motion components.

**Global Footprint**

With direct sales, engineering support, manufacturing facilities, and distributors across North America, Europe, and Asia, we're close to OEMs worldwide. Our proximity helps speed delivery and lend support where and when they're needed.

**Financial and Operational Stability**

Kollmorgen is part of Danaher Corporation, our \$13B parent company. A key driver in the growth of all Danaher divisions is the Danaher Business System, which relies on the principle of "kaizen" – or continuous improvement. Using world-class tools, cross-disciplinary teams of exceptional people evaluate processes and develop plans that result in superior performance.

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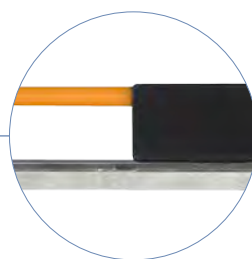
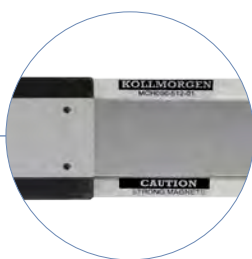
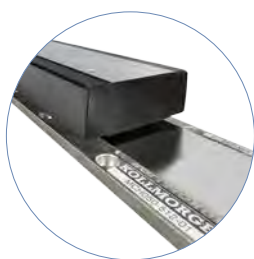
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# Direct Drive Linear Motor

Our direct drive linear motor series provide new dimension in performance with high throughput, accuracy, and zero maintenance. The product line are frameless, permanent magnet, three phase, brushless servomotors. The product line consists of two fundamental constructions, Ironless (slotless) and Ironcore. Ironless motors have no attractive force between the frameless components and zero cogging for the ultra smooth motion. Ironcore motors provide the highest force per frame size. They feature a anti-cogging design which yields extremely smooth operation.

## The Benefits of Direct Drive Linear Motor

- |   |  |
|---|--|
| <ul style="list-style-type: none"> <li>• Zero Maintenance with Greater Accuracy and Higher Bandwidth</li> </ul>   | <ul style="list-style-type: none"> <li>• Smoother velocity and reduced audible noise</li> <li>• Power transmission without backlash</li> <li>• Transmission elements such as couplings, toothed belts, ball/lead screws, rack &amp; pinions, and other fitted components can be eliminated</li> <li>• No gears or screws, no lubrication required</li> <li>• Improved machine reliability</li> </ul> |
| <ul style="list-style-type: none"> <li>• Wide Range of Sizes and Force to Cover any Linear Application</li> </ul> | <ul style="list-style-type: none"> <li>• Increased performance for the entire system</li> <li>• Flat, compact drive solution</li> <li>• Easily mix / match motors and drives</li> <li>• Real-life acceleration up to 10 G</li> </ul>   |
| <ul style="list-style-type: none"> <li>• Simplified, High Force Permanent Magnet Design</li> </ul>                | <ul style="list-style-type: none"> <li>• Higher bandwidth and faster response than ball/lead screws or rack &amp; pinion solutions</li> <li>• Rapid indexing of heavy loads with peak force up to 12700 N</li> <li>• Fewer parts and lower cost of ownership</li> <li>• More compact machine design</li> <li>• No cogging and no attractive force (ironless motors)</li> </ul>                       |



# Direct Drive Linear Motor Overview

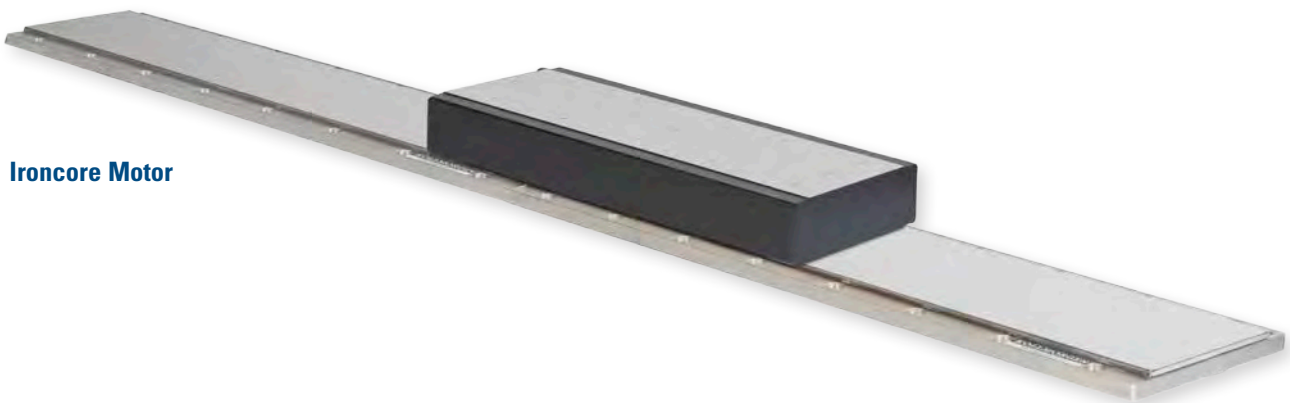
## Kollmorgen Direct Drive Linear DDL Motor Series

Kollmorgen supplied its first linear motors in the late 1970's for use in precision X-Y tables and coating systems. These were brush DC motors using the Kollmorgen patented push-through commutator bar method. This led to development in the early 1980's of the brushless versions of the linear motor which were used in film processing applications where smooth, high stiffness, linear motion was required. During the past 30 years, advances in permanent magnet material, power semiconductors, and microprocessor technology have been the enablers for increased performance and lower costs for linear motors.

*DDL motors series ICH comply with the Low Voltage Directive 2014/35/EC for installation in a machine. Safety depends upon installing and configuring motor per the manufacturer's recommendations. The machine in which this product is to be installed must conform to the provisions of EC directive 2014/30/EC.*



**Ironless Motor**



**Ironcore Motor**

## Standard Product Features

### Ironcore:

- Peak force ICH series: 405 N to 12726 N
- Continuous force ICH series: 175 N to 5341 N
- Anti-cogging technique for minimal cogging without magnet skewing
- High motor constant ( $K_m$ )
- High force density
- Thermal protection PTC and KTY
- Stainless steel magnet way covers
- Isolation system for 480 V AC

### Ironless:

- Peak force 60 N to 1600 N
- Continuous force 21 N to 450 N
- Zero cogging
- Zero attractive force
- Smooth motion for speed as low as 1 micron/second
- Low mass coil assembly for high acceleration
- Isolation system for 230 V AC

### All Motors:

- Zero contact, zero maintenance, brushless design
- 3 phase sinusoidal commutation
- Peak accelerations easily above 10 G
- High position accuracy and resolution
- Very low settling time
- Low thermal losses
- Modular magnet design

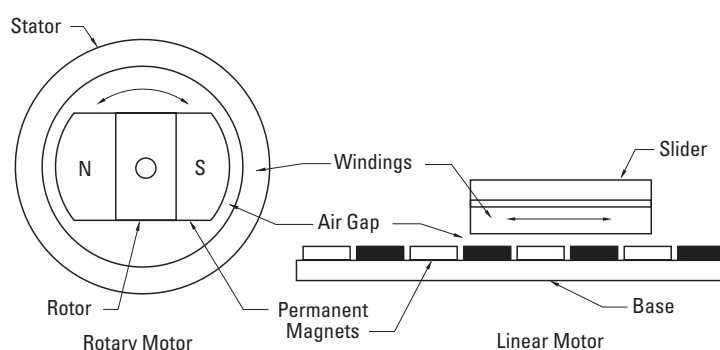
### Standard Options:

- Hall effect feedback (digital)
- Thermal protection thermistor (PTC, ironless)
- Cable options
- Winding options

Our Direct Drive Linear (DDL) motor series are frameless permanent magnet, three phase brushless servomotors. Fundamentally, a linear motor is a rotary motor that is rolled out flat.

The two primary components of permanent magnet brushless rotary motors are the stator (primary coils) and the rotor (secondary or rotating magnets). In brushless linear motors the rotor is rolled out flat to become the magnet track (also called the magnet way). The primary coils of the rotary motor are rolled out flat to become the coil assembly (also sometimes called the slider).

In most brushless linear motor applications it is typical for the magnet way to be stationary and the coil assembly to be in motion, because of the relative masses of the two components. But it is also perfectly acceptable and sometimes advantageous to reverse this arrangement. The basic electromagnetic operating principles are the same in either case and are identical to those of a rotary motor.



**Rotary Motor Rolled Out Flat**

### Direct Drive Linear Motor Options

Two types of linear motors are available, Ironcore and Ironless. Each one provides characteristics and features that are optimal depending upon the application. Ironcore motors have coils wound on silicon steel laminations, to maximize the generated force, with a single sided magnet way.

Using an innovative electromagnetic design, DDL linear motors have the highest rated force per size, a high  $K_m$  motor constant (equals low thermal losses), and low cogging forces without the need for skewing of the magnets. The high thrust forces possible with these motors make them ideal for accelerating and moving high masses, and maintaining

stiffness during machining or process forces. Ironless motors have no iron, or slots for the coils to be wound on.

Therefore, these motors have zero cogging, a very light mass, and absolutely no attractive forces between the coil assembly and the magnet way. These characteristics are ideal for applications requiring very low bearing friction, high acceleration of lighter loads, and for maximizing constant velocity, even at ultra low speeds. The modular magnet ways consists of a double row of magnets to maximize the generated thrust force and to provide a flux return path for the magnetic circuit.

### Feedback Types

All brushless motors require feedback for commutation. For a linear motor, commutation feedback can also be accomplished with a variety of methods. Digital or linear Hall effect devices are available from Kollmorgen for the DDL motor series which allow the drive electronics to commutate the linear motors in a manner identical to rotary motors. For exceptionally smooth motion requirements, sinusoidal drive electronics using digital Hall effects, provide sinusoidal drive currents

to the motor for the best constant force and velocity performance. As an alternative, it is typical for linear motor applications to have a linear encoder present in the system for position feedback. It is increasingly common today for drive amplifiers to derive the necessary commutation information directly from this linear encoder, either with or without supplemental digital Hall effect devices on startup.



# Direct Drive Linear Motor Overview

## Advantages

### Wide Speed Range

Since the frameless parts of the linear motor are non-contact, and no limitations of a mechanical transmission are present, both very high speeds and very low speeds are easily obtainable. Speeds are truly not limited by the motor. Instead, by eliminating the mechanical transmission, speed becomes limited by other elements in the system such as the linear bearings, and the achievable bandwidth from any feedback devices. Application speeds of greater than 5 meters per second or less than 1 micron per second are typically achievable. In comparison, mechanical transmissions such as ball screws are commonly limited to linear speeds of 0.5 to 0.7 meters per second because of resonances and wear. In addition to a wide speed range, linear motors, both ironcore and ironless, have excellent constant velocity characteristics, typically better than  $\pm 0.01\%$  speed variation.

### High System Dynamics

In addition to high speed capability, direct drive linear motors are capable of very high accelerations. Limited only by the system bearings, accelerations of 3 to 5 G are quite typical for the larger motors and accelerations exceeding 10 G are easily achievable for smaller motors.

### Easy Selection process:

1. Determine peak and continuous force required for your applications (see our applications section on pages 38-41)
2. Use the motor selection guide on pages 8-9 to choose your motor
3. Refer to the appropriate pages in the data publication for technical details
4. Build model number for ordering using pages 42-44

### Smooth Operation and Positional Accuracy

Both ironless and ironcore motors exhibit very smooth motion profiles due to the inherent motor design of Kollmorgen's DDL series. Cogging, which is a component of force, is greatly reduced in the ironcore designs and is zero in the ironless designs. As a result, these direct drive linear motors provide very low force and velocity ripple for ultra smooth motion. Positioning accuracies are limited only by the feedback resolution, and sub-micron resolutions are commonly achievable.

### Unlimited Travel

With the DDL motor series, magnet ways are made in 4 modular sections: 64 mm, 128 mm, 256 mm and 512 mm long. Each module can be added in unlimited numbers to any other module to allow for unlimited travel. Whether the travel required is 1mm or 100 meters the DDL series can accommodate the need.

### No Wear or Maintenance

Linear motors have few components, therefore the need for ball screw components such as nuts, bearing blocks, couplings, motor mounts and the need to maintain these components have been eliminated. Very long life and clean operation, with no lubrication or maintenance of these parts are the result.

### Integration of Components is Much Simpler

Frameless linear motors require much fewer components than rotary motors with mechanical transmissions. A 0.9mm airgap for the ironcore design and 0.5 mm airgap for the ironless design is the only alignment of the frameless linear motor components that is necessary. No critical alignments are required as with ball screws. Straightness of travel as provided by the system linear bearings is more than sufficient for the Kollmorgen linear motors.

### Typical Applications for Linear Motors Include:

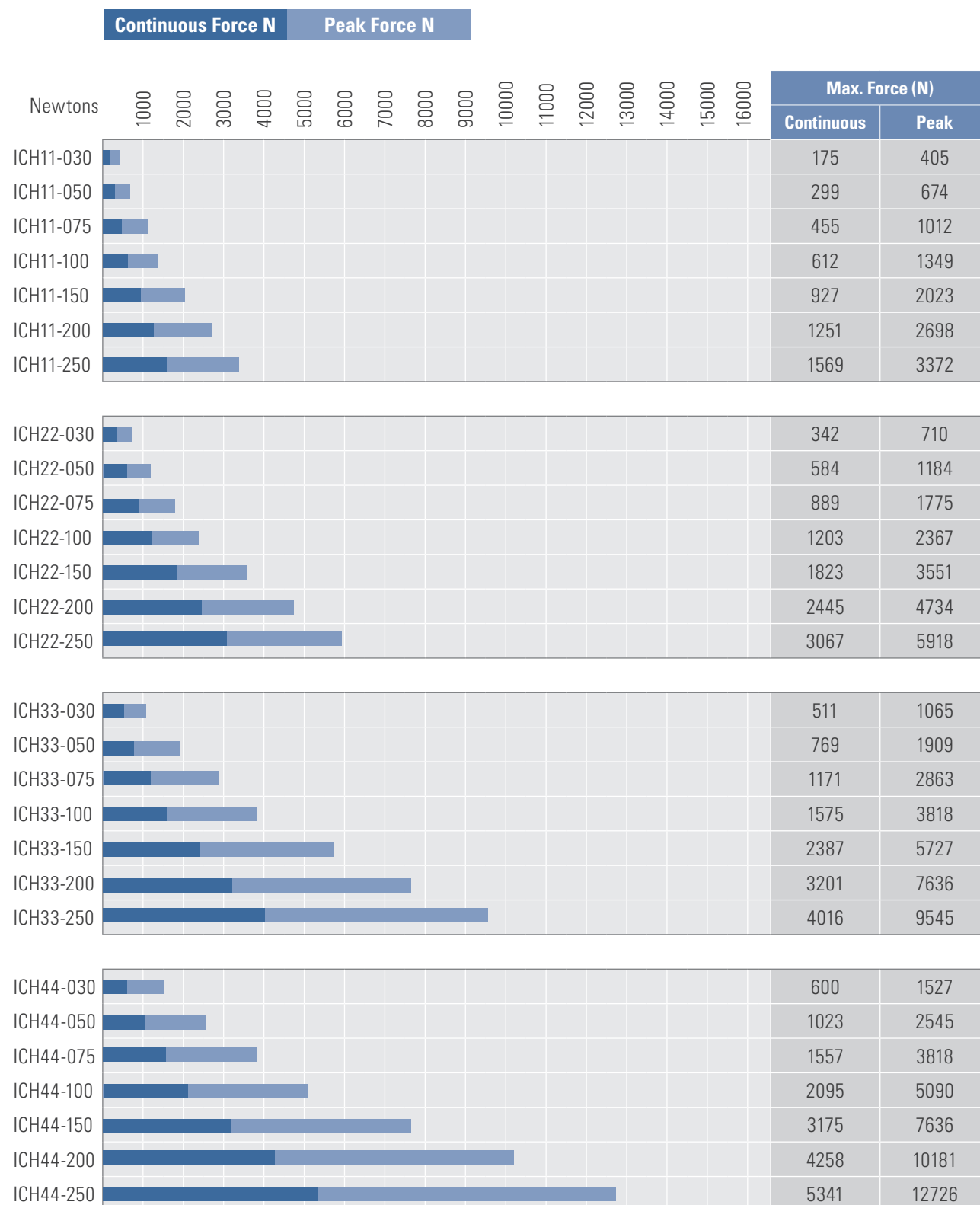
Machine Tool	Patient table
Drilling	Handling systems
Milling	Measurement/ Inspection
Grinding	Coordinate measurement machines
Laser cutting	Electronic assembly
Cam grinding	Pick-and-place machines
Semiconductor	Component insertion
Wafer handling process	Screen printers
Wafer-inspection	Adhesive dispensers
Wafer slicing	PC-board inspection. drilling
Tab bonding	Other applications include:
Wire bonding	Flight Simulators
Ion implantation	Acceleration sleds
Lithography	Catapult
Textile	G-Force measurement
Carpet tufting	Textile
Plasma cutting	Carpet tufting
Polishing	
Preform injection (plastics)	



## Notes

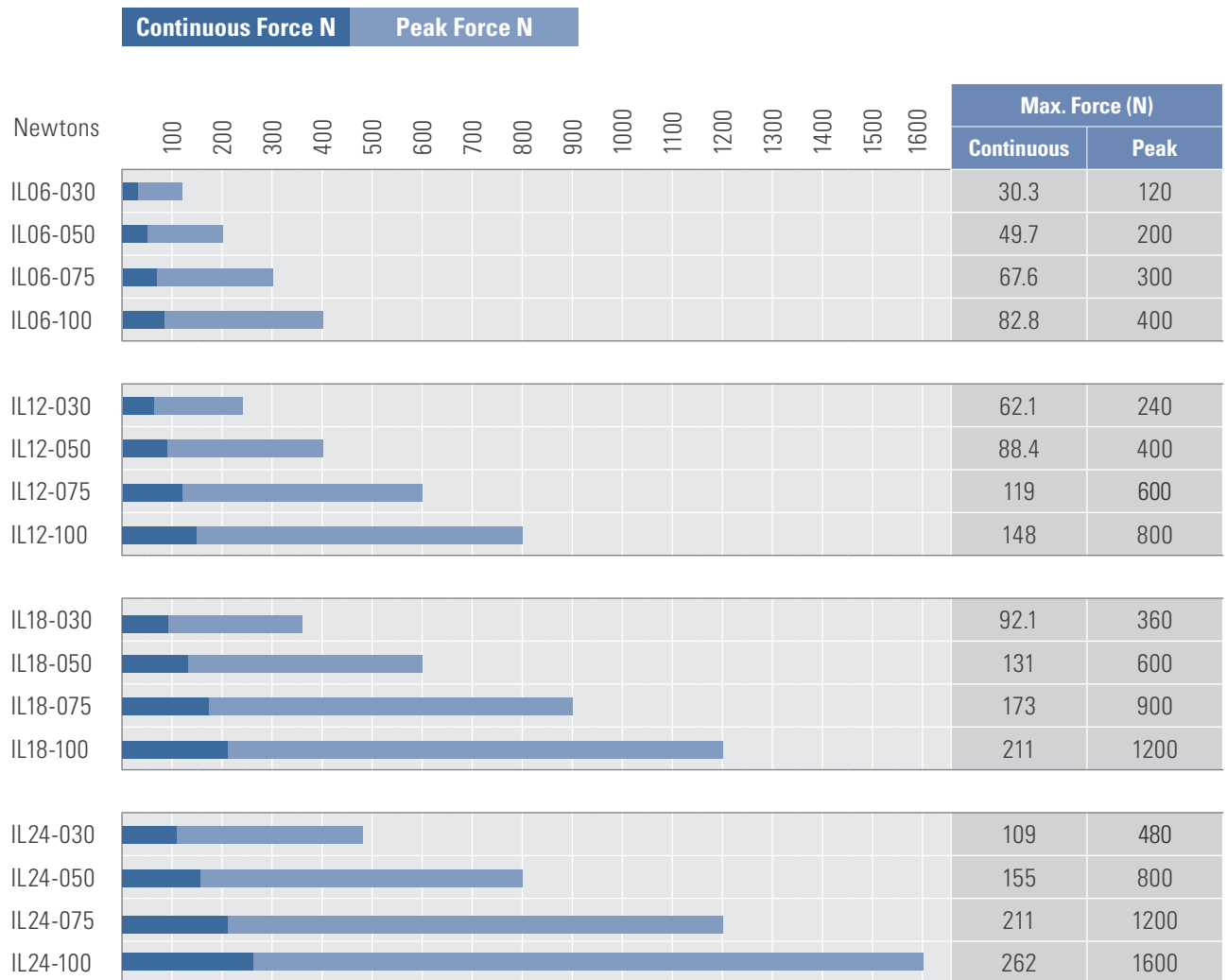
# Direct Drive Linear Motor Summary

## Ironcore Linear Motors



# Direct Drive Linear Motor Summary

## Ironless Linear Motors



# ICH11 Performance Data

## Ironcore Motors Series

Rated Performance	Symbol	Units	ICH11-030		ICH11-050		ICH11-075		ICH11-100		ICH11-150		ICH11-200		ICH11-250	
Peak Force	Fp	N	405		674		1012		1349		1909		2545		3182	
Continuous Force @ Tmax (1)	Fc	N	175		299		455		612		1000		1200		1507	
Motor Constant @ 25°C	Km	N/√W	26		38		49		59		72		85		96	
Electrical Specifications (2)																
Winding Code (5)			A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5
Peak Current	Ip	Arms	8.9	15.5	8.9	15.5	8.9	15.5	8.9	15.5	15.3	26.5	15.3	26.5	15.3	26.5
Continuous Current @Tmax	Ic	Arms	2.9	5.0	2.9	5.1	3.0	5.2	3.0	5.2	5.9	10.2	5.2	9.0	5.2	9.1
Electrical Resistance @ 25°C ±10%	Rm	Ohms L-L	3.8	1.3	5.1	1.7	6.7	2.2	8.3	2.8	3.8	1.3	4.9	1.6	5.9	2.0
Electrical Inductance ±20%	L	mH L-L	47	16	78	26	117	39	156	52	80	27	106	35	133	44
Back EMF Constant @ 25°C ±10%	Ke	V <sub>peak</sub> /(m/s) L-L	49	28	82	47	122	71	163	94	141	81	188	108	235	135
Force Constant @ 25°C ±10%	Kf	N/Arms	61	35	102	59	152	88	203	117	173	100	230	133	287	166
Mechanical Specifications																
Coil Assembly Mass ±15%	Mc	kg	2.5		3.5		4.8		6.1		8.6		11.2		13.8	
Magnetic Way Type			MCH030		MCH050		MCH075		MCH100		MCH150		MCH200		MCH250	
Magnetic Way Mass ±15%	Mw	kg/m	5.4		7.6		10.4		13.2		18.8		24.4		30.0	
Figures of Merit and Additional Data																
Electrical Time Constant	Te	ms	12.5		15.4		17.5		18.8		21.0		21.8		22.4	
Max.Theoretical Acceleration (3)	Amax	m/s²	161		191		210		222		234		241		245	
Max. Allowable Coil Temp. (4)	Tmax	°C	145		145		145		145		145		145		145	
Cable Diameter	Dc	mm	12.4		12.4		12.4		12.4		12.4		12.4		12.4	

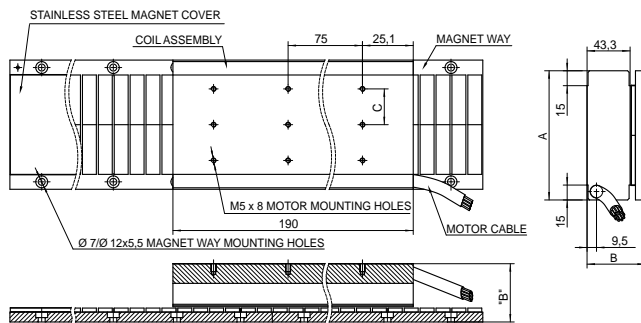
### Notes:

1. The motor continuous force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings are available on request. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.
5. Winding phase connection: A1: Y (star) windings, A5: Δ (triangle) windings



# ICH11 Outline Drawings

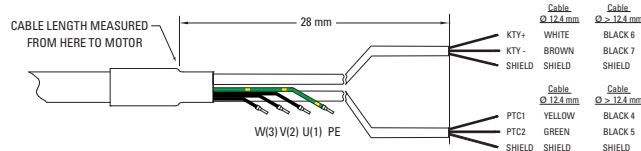
## Ironcore Motors Series



Motor Coil Type	Coil Width	Motor Height	Hole Grid Spacing
	A (mm)	B (mm)	C (mm)
ICH11-030	60.0 ± 1.0	58.6 ± 0.1	16.0
ICH11-050	80.0 ± 1.0	58.6 ± 0.1	36.0
ICH11-075	105.0 ± 1.0	58.6 ± 0.1	32.0
ICH11-100	130.0 ± 1.0	58.6 ± 0.1	36.0
ICH11-150	180.0 ± 1.0	60.6 ± 0.1	32.0
ICH11-200	230.0 ± 1.0	60.6 ± 0.1	36.0
ICH11-250	280.0 ± 1.0	62.6 ± 0.1	32.0

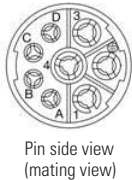
Resultant airgap = 0.9 mm nominal (0.5 mm minimum) when components are set up to dimension "B" in table above.  
Number of holes and typical installation of multiple ironcore magnet assemblies: please refer to page 21

## Cable Option Flying Leads



Leads	Cable Length (mm)
C1	400
C2	200
C3	100
C4	1200

## Cable Option Connector on the Cable (Only available for Motors with $I_c < 9$ A)



Extension with pins:  
BKUA-MR24-42-0035-000  
Suggested mating connector  
BSTA-108-FR05-08-0036-000 (cable mounted) or  
BDFA-108-FR05-00-0150-000 (flange mounted)

Connector	Cable Length (mm)
P1	400
P2	200
P3	100
P4	1200

Shield is connected to motor core and connectors case

## Cable Types

Motor Coil Type	Cable Type: OLFLEX-SERVO 709 CY 4G ...
ICH11-030 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH11-050 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH11-075 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH11-100 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH11-150 A1	0.75+2x(2X0.34)Ø12.4
ICH11-150 A5	0.75+2x(2X0.34)Ø12.4
ICH11-200 A1	0.75+2x(2X0.34)Ø12.4
ICH11-200 A5	0.75+2x(2X0.34)Ø12.4
ICH11-250 A1	0.75+2x(2X0.34)Ø12.4
ICH11-250 A5	0.75+2x(2X0.34)Ø12.4

## Cable Wire Nomenclature

Function	Cable Ø 12.4 mm	Cable > Ø 12.4 mm	Plug BKUA (Option) (1)
U	Black 1	Black 1	1
V	Black 2	Black 2	3
W	Black 3	Black 3	4
PE	Green/Yellow	Green/Yellow	PE
PTC1	Yellow	Black 5	A
PTC2	Green	Black 6	B
KTY+	White	Black 7	C
KTY-	Brown	Black 8	D

Note 1: Option available only for motors with  $I_c < 15$  A

# ICH22 Performance Data

## Ironcore Motors Series

Rated Performance	Symbol	Units	ICH22-030		ICH22-050		ICH22-075		ICH22-100		ICH22-150		ICH22-200		ICH22-250	
Peak Force	Fp	N	710		1184		1775		2367		3551		4734		5918	
Continuous Force @ Tmax (1)	Fc	N	342		584		889		1203		1823		2445		3067	
Motor Constant @ 25°C	Km	N/√W	37		53		69		83		106		125		141	
Electrical Specifications (2)																
Winding Code (5)			A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5
Peak Current	Ip	Arms	8.9	15.5	8.9	15.5	17.9	30.9	30.6	53.0	30.6	53.0	30.6	53.0	30.6	53.0
Continuous Current @Tmax	Ic	Arms	2.8	4.9	2.9	5.0	5.9	10.2	10.2	17.7	10.4	17.9	10.4	18.0	10.5	18.1
Electrical Resistance @ 25°C ±10%	Rm	Ohms L-L	7.5	2.5	10.1	3.4	3.3	1.1	1.4	0.46	1.9	0.65	2.5	0.83	3.0	1.0
Electrical Inductance ±20%	L	mH L-L	94	31	156	52	59	20	27	9	40	13	53	18	66	22
Back EMF Constant @ 25°C ±10%	Ke	V <sub>peak</sub> /(m/s) L-L	98	57	163	94	122	71	95	55	143	82	190	110	237	137
Force Constant @ 25°C ±10%	Kf	N/Arms	121	70	202	117	151	87	117	68	176	102	235	135	293	169
Mechanical Specifications																
Coil Assembly Mass ±15%	Mc	kg	4.9		6.8		9.3		11.8		16.8		21.7		26.7	
Magnetic Way Type			MCH030		MCH050		MCH075		MCH100		MCH150		MCH200		MCH250	
Magnetic Way Mass ±15%	Mw	kg/m	5.4		7.6		10.4		13.2		18.8		24.4		30.0	
Figures of Merit and Additional Data																
Electrical Time Constant	Te	ms	12.5		15.4		17.5		19.1		20.6		21.4		21.9	
Max.Theoretical Acceleration(3)	Amax	m/s²	146		173		190		201		212		218		222	
Max. Allowable Coil Temp. (4)	Tmax	°C	145		145		145		145		145		145		145	
Cable Diameter	Dc	mm	12.4		12.4		12.4		12.4		13.6		12.4		13.6	

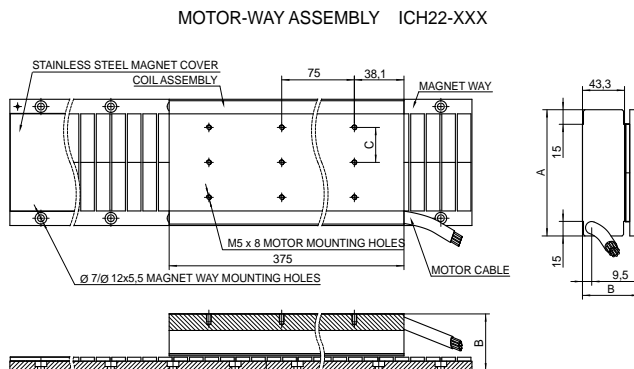
### Notes:

1. The motor continuous force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings are available on request. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.
5. Winding phase connection: A1: Y (star) windings, A5: Δ (triangle) windings



# ICH22 Outline Drawings

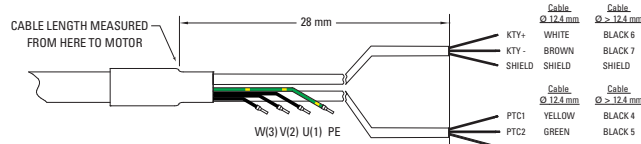
## Ironcore Motors Series



Resultant airgap = 0.9 mm nominal (0.5 mm minimum) when components are set up to dimension "B" in table above.  
Number of holes and typical installation of multiple ironcore magnet assemblies: please refer to page 21

Motor Coil Type	Coil Width	Motor Height	Hole Grid Spacing
	A (mm)	B (mm)	C (mm)
ICH22-030	60.0 ± 1.0	58.6 ± 0.1	16.0
ICH22-050	80.0 ± 1.0	58.6 ± 0.1	36.0
ICH22-075	105.0 ± 1.0	58.6 ± 0.1	32.0
ICH22-100	130.0 ± 1.0	58.6 ± 0.1	36.0
ICH22-150	180.0 ± 1.0	60.6 ± 0.1	32.0
ICH22-200	230.0 ± 1.0	60.6 ± 0.1	36.0
ICH22-250	280.0 ± 1.0	62.6 ± 0.1	32.0

## Cable Option Flying Leads



Leads	Cable Length (mm)
C1	400
C2	200
C3	100
C4	1200

## Cable Option Connector on the Cable (Only available for Motors with $I_c < 9$ A)



Extension with pins:  
BKUA-MR24-42-0035-000

Suggested mating connector  
BSTA-108-FR05-08-0036-000 (cable mounted) or  
BDFA-108-FR05-00-0150-000 (flange mounted)

Connector	Cable Length (mm)
P1	400
P2	200
P3	100
P4	1200

Shield is connected to motor core and connectors case

## Cable Types

Motor Coil Type	Cable Type: OLFLEX-SERVO 709 CY 4G ...
ICH22-030 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH22-050 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH22-075 A1	0.75+2x(2X0.34)Ø12.4
ICH22-075 A5	0.75+2x(2x0.34)Ø12.4
ICH22-100 A1	0.75+2x(2x0.34)Ø12.4
ICH22-100 A5	1.00+2x(2x0.75)Ø13.6
ICH22-150 A1	0.75+2x(2x0.34)Ø12.4
ICH22-150 A5	1.00+2x(2x0.75)Ø13.6
ICH22-200 A1	0.75+2x(2x0.34)Ø12.4
ICH22-200 A5	1.00+2x(2x0.75)Ø13.6
ICH22-250 A1	0.75+2x(2x0.34)Ø12.4
ICH22-250 A5	1.00+2x(2x0.75)Ø13.6

## Cable Wire Nomenclature

Function	Cable Ø 12.4 mm	Cable > Ø 12.4 mm	Plug BKUA (Option) (1)
U	Black 1	Black 1	1
V	Black 2	Black 2	3
W	Black 3	Black 3	4
PE	Green/Yellow	Green/Yellow	PE
PTC1	Yellow	Black 5	A
PTC2	Green	Black 6	B
KTY+	White	Black 7	C
KTY-	Brown	Black 8	D

Note 1: Option available only for motors with  $I_c < 15$  A



# ICH33 Performance Data

## Ironcore Motors Series

Rated Performance	Symbol	Units	ICH33-030		ICH33-050		ICH33-075		ICH33-100		ICH33-150		ICH33-200		ICH33-250	
Peak Force	Fp	N	1065		1909		2863		3818		5727		7636		9545	
Continuous Force @ Tmax (1)	Fc	N	511		769		1171		1575		2387		3201		4016	
Motor Constant @ 25°C	Km	N/√W	45		65		85		101		128		151		171	
Electrical Specifications (2)																
Winding Code (5)			A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5
Peak Current	Ip	Arms	8.9	15.5	30.6	53.0	30.6	53.0	30.6	53.0	30.6	53.0	45.9	79.5	45.9	79.5
Continuous Current @Tmax	Ic	Arms	2.8	4.9	8.8	15.2	8.9	15.5	9.0	15.6	9.1	15.8	13.8	23.8	13.8	23.9
Electrical Resistance @ 25°C ±10%	Rm	Ohms L-L	11.3	3.8	1.3	0.42	1.7	0.56	2.1	0.70	2.9	0.97	1.7	0.55	2.0	0.67
Electrical Inductance ±20%			L	mH L-L	141	47	20	7	30	10	40	13	60	20	35	12
Back EMF Constant @ 25°C ±10%	Ke	V <sub>peak</sub> /(m/s) L-L	147	85	72	41	107	62	143	82	214	123	190	110	237	137
Force Constant @ 25°C±10%	Kf	N/Arms	182	105	88	51	131	76	175	101	262	151	233	134	291	168
Mechanical Specifications																
Coil Assembly Mass ±15%	Mc	kg	7.2		10.2		13.8		17.5		24.9		32.2		39.6	
Magnetic Way Type			MCH030		MCH050		MCH075		MCH100		MCH150		MCH200		MCH250	
Magnetic Way Mass ±15%	Mw	kg/m	5.4		7.6		10.4		13.2		18.8		24.4		30.0	
Figures of Merit and Additional Data																
Electrical Time Constant	Te	ms	12.5		15.6		17.8		19.1		20.6		21.4		21.9	
Max.Theoretical Acceleration(3)	Amax	m/s²	148		188		207		218		230		237		241	
Max. Allowable Coil Temp. (4)	Tmax	°C	145		145		145		145		145		145		145	
Cable Diameter	Dc	mm	12.4		12.4	13.6	12.4	13.6	12.4	13.6	12.4	13.6	12.4	16.7	12.4	16.7

### Notes:

1. The motor continuous force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings are available on request. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.
5. Winding phase connection: A1: Y (star) windings, A5: Δ (triangle) windings



## ICH33 PERFORMANCE DATA

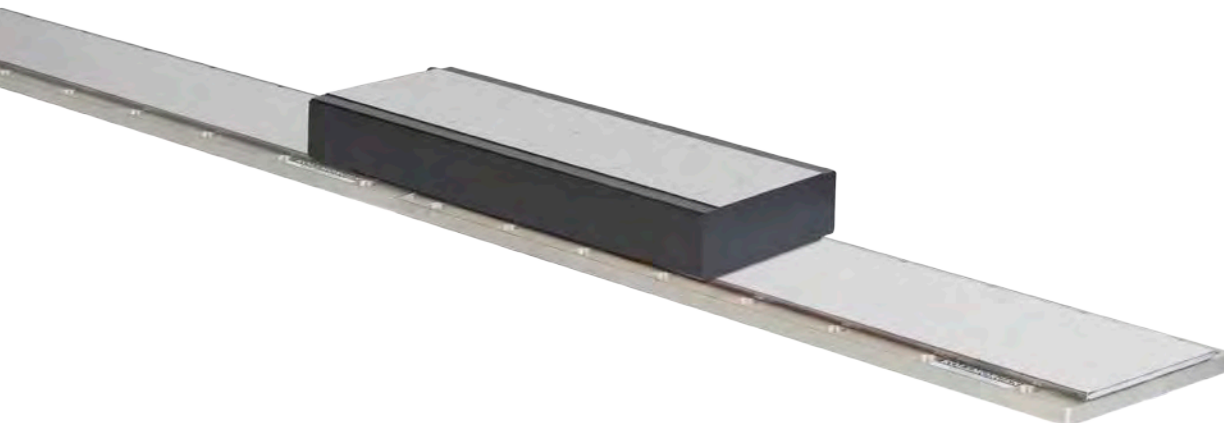
# ICH44 Performance Data

## Ironcore Motors Series

Rated Performance	Symbol	Units	ICH44-030		ICH44-050		ICH44-075		ICH44-100		ICH44-150		ICH44-200		ICH44-250	
Peak Force	Fp	N	1527		2545		3818		5090		7636		10181		12726	
Continuous Force @ Tmax (1)	Fc	N	600		1023		1557		2095		3175		4258		5341	
Motor Constant @ 25°C	Km	N/√W	52		75		98		117		148		175		198	
Electrical Specifications (2)																
Winding Code (5)			A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5	A1	A5
Peak Current	Ip	Arms	15.3	26.5	15.3	26.5	30.6	53.0	30.6	53.0	61.2	106.0	61.2	106.0	61.2	106.0
Continuous Current @Tmax	Ic	Arms	4.3	7.4	4.4	7.6	8.9	15.4	9.0	15.6	18.2	31.5	18.3	31.7	18.4	31.8
Electrical Resistance	Rm	Ohms L-L	5.1	1.7	6.8	2.3	2.2	0.75	2.8	0.93	0.97	0.32	1.2	0.41	1.5	0.50
@ 25°C ±10%																
Electrical Inductance ±20%	L	mH L-L	64	21	106	35	40	13	53	18	20	7	27	9	33	11
Back EMF Constant	Ke	V <sub>peak</sub> /(m/s) L-L	115	66	191	110	143	82	190	110	143	82	190	110	237	137
@25°C ±10%																
Force Constant @ 25°C ±10%	Kf	N/Arms	140	81	234	135	175	101	233	135	175	101	233	134	291	168
Mechanical Specifications																
Coil Assembly Mass ±15%	Mc	kg	9.6		13.5		18.3		23.2		33.0		42.7		52.5	
Magnetic Way Type			MCH030		MCH050		MCH075		MCH100		MCH150		MCH200		MCH250	
Magnetic Way Mass ±15%	Mw	kg/m	5.4		7.6		10.4		13.2		18.8		24.4		30.0	
Figures of Merit and Additional Data																
Electrical Time Constant	Te	ms	12.6		15.6		17.8		19.1		20.6		21.4		21.9	
Max.Theoretical Acceleration(3)	Amax	m/s²	160		189		208		219		232		238		242	
Max. Allowable Coil Temp. (4)	Tmax	°C	145		145		145		145		145		145		145	
Cable Diameter	Dc	mm	12.4		12.4		12.4	13.6	12.4	13.6	13.6	16.7	13.6	16.7	14.8	16.7

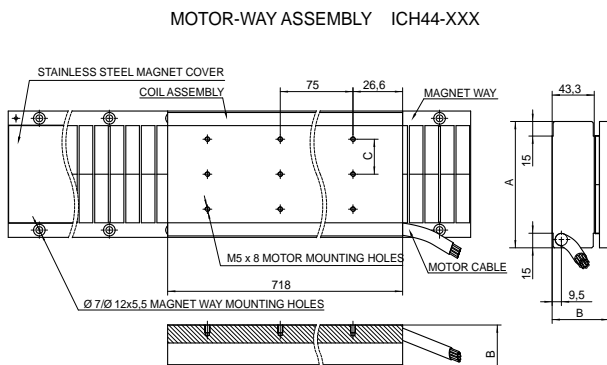
### Notes:

1. The motor continuous force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings are available on request. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.
5. Winding phase connection: A1: Y (star) windings, A5: Δ (triangle) windings



# ICH44 Outline Drawings

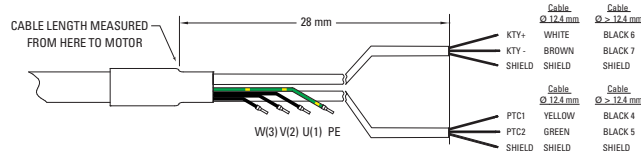
## Ironcore Motors Series



Resultant airgap = 0.9 mm nominal (0.5 mm minimum) when components are set up to dimension "B" in table above.  
Number of holes and typical installation of multiple ironcore magnet assemblies: please refer to page 21

Motor Coil Type	Coil Width	Motor Height	Hole Grid Spacing
	A (mm)	B (mm)	C (mm)
ICH44-030	60.0 ± 1.0	58.6 ± 0.1	16.0
ICH44-050	80.0 ± 1.0	58.6 ± 0.1	36.0
ICH44-075	105.0 ± 1.0	58.6 ± 0.1	32.0
ICH44-100	130.0 ± 1.0	58.6 ± 0.1	36.0
ICH44-150	180.0 ± 1.0	60.6 ± 0.1	32.0
ICH44-200	230.0 ± 1.0	60.6 ± 0.1	36.0
ICH44-250	280.0 ± 1.0	62.6 ± 0.1	32.0

## Cable Option Flying Leads



Leads	Cable Length (mm)
C1	400
C2	200
C3	100
C4	1200

## Cable Option Connector on the Cable (Only available for Motors with $I_c < 9 A$ )



Extension with pins:  
BKUA-MR24-42-0035-000

Suggested mating connector  
BSTA-108-FR05-08-0036-000 (cable mounted) or  
BDFA-108-FR05-00-0150-000 (flange mounted)

Connector	Cable Length (mm)
P1	400
P2	200
P3	100
P4	1200

Shield is connected to motor core and connectors case

## Cable Types

Motor Coil Type	Cable Type: OLFLEX-SERVO 709 CY 4G ...
ICH44-030 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH44-050 A1/A5	0.75+2x(2X0.34)Ø12.4
ICH44-075 A1	0.75+2x(2x0.34)Ø12.4
ICH44-075 A5	1.00+2x(2x0.75)Ø13.6
ICH44-100 A1	0.75+2x(2x0.34)Ø12.4
ICH44-100 A5	1.00+2x(2x0.75)Ø13.6
ICH44-150 A1	1.00+2x(2x0.75)Ø13.6
ICH44-150 A5	4.00+2x(2x1.00+2x1.50)Ø16.7
ICH44-200 A1	1.00+2x(2x0.75)Ø13.6
ICH44-200 A5	4.00+2x(2x1.00+2x1.50)Ø16.7
ICH44-250 A1	1.50+2x(2x0.75)Ø14.8
ICH44-250 A5	4.00+2x(2x1.00+2x1.50)Ø16.7

## Cable Wire Nomenclature

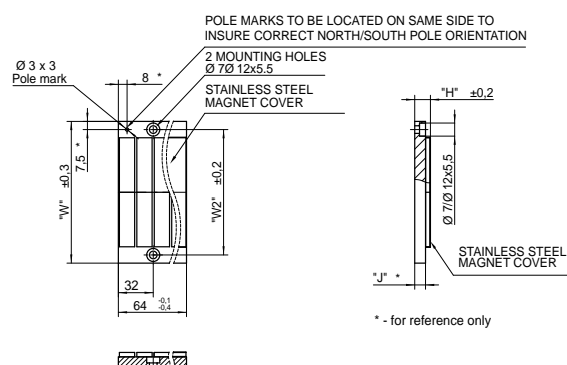
Function	Cable Ø 12.4 mm	Cable > Ø 12.4 mm	Plug BKUA (Option) (1)
U	Black 1	Black 1	1
V	Black 2	Black 2	3
W	Black 3	Black 3	4
PE	Green/Yellow	Green/Yellow	PE
PTC1	Yellow	Black 5	A
PTC2	Green	Black 6	B
KTY+	White	Black 7	C
KTY-	Brown	Black 8	D

Note 1: Option available only for motors with  $I_c < 15 A$

# Ironcore Magnet Ways

## MCHxxx-064

MCHXXX-064-01

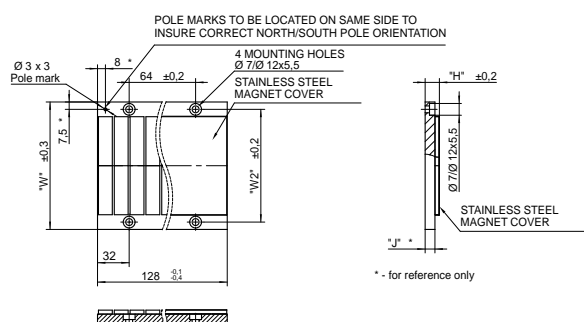


Magnet assemblies are modular and can be installed in multiples of same or alternate lengths. Standard lengths are shown below.

Magnetic Way Type	Assembly Width W (mm)	Mounting Hole Width W2 (mm)	J (mm)	H With Cover (mm)
MCH030-064	60.0	45.0	10.0	14.4
MCH050-064	80.0	65.0	10.0	14.4
MCH075-064	105.0	90.0	10.0	14.4
MCH100-064	130.0	115.0	10.0	14.4
MCH150-064	180.0	165.0	12.0	16.4
MCH200-064	230.0	215.0	12.0	16.4
MCH250-064	280.0	265.0	14.0	18.4

## MCHxxx-128

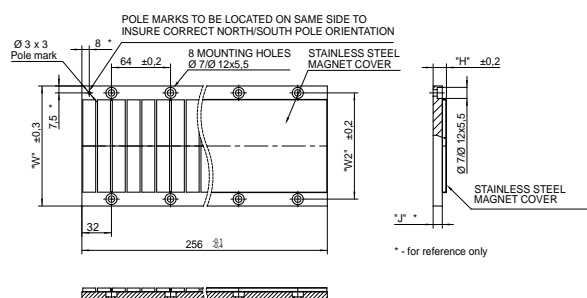
MCHXXX-128-01



Magnetic Way Type	Assembly Width W (mm)	Mounting Hole Width W (mm)	J (mm)	H With Cover (mm)
MCH030-128	60.0	45.0	10.0	14.4
MCH050-128	80.0	65.0	10.0	14.4
MCH075-128	105.0	90.0	10.0	14.4
MCH100-128	130.0	115.0	10.0	14.4
MCH150-128	180.0	165.0	12.0	16.4
MCH200-128	230.0	215.0	12.0	16.4
MCH250-128	280.0	265.0	14.0	18.4

## MCHxxx-256

MCHXXX-256-01

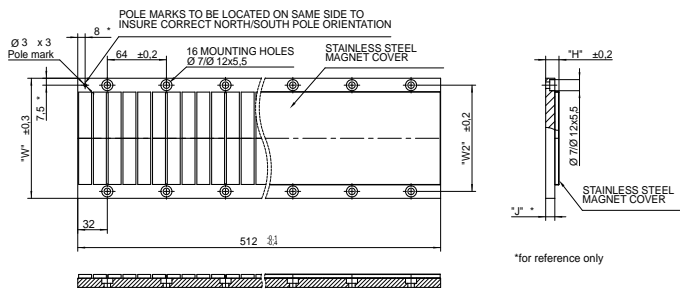


Magnetic Way Type	Assembly Width W (mm)	Mounting Hole Width W2 (mm)	J (mm)	H With Cover (mm)
MCH030-256	60.0	45.0	10.0	14.4
MCH050-256	80.0	65.0	10.0	14.4
MCH075-256	105.0	90.0	10.0	14.4
MCH100-256	130.0	115.0	10.0	14.4
MCH150-256	180.0	165.0	12.0	16.4
MCH200-256	230.0	215.0	12.0	16.4
MCH250-256	280.0	265.0	14	18.4

\* Note: Flatness and height of magnet ways is defined at fastened to the flat base.

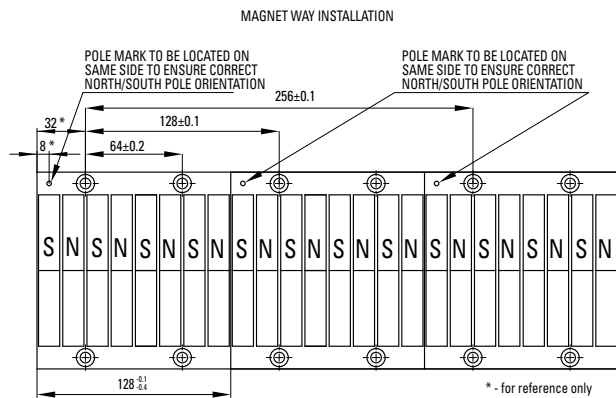
## MCHxxx-512

MCHXXX-512-01



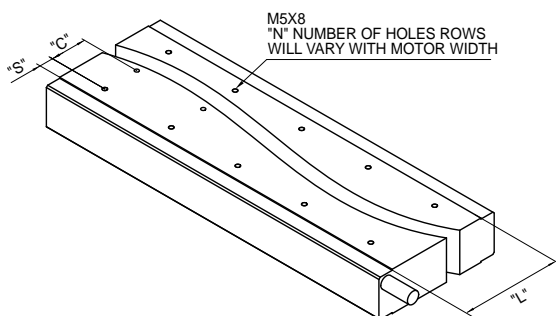
Magnetic Way Type	Assembly Width W (mm)	Mounting Hole Width W2 (mm)	J (mm)	H With Cover (mm)
MCH030-512	60.0	45.0	10.0	14.4
MCH050-512	80.0	65.0	10.0	14.4
MCH075-512	105.0	90.0	10.0	14.4
MCH100-512	130.0	115.0	10.0	14.4
MCH150-512	180.0	165.0	12.0	16.4
MCH200-512	230.0	215.0	12.0	16.4
MCH250-512	280.0	265.0	14	18.4

## Typical Installation of Multiple Ironcore Magnet Assemblies



Magnet Way widths correspond to the mating coil assembly width. Magnet Way assemblies are modular and come in standard lengths: 64, 128, 256, 512 mm. Multiple magnet assemblies can be installed to obtain the desired length. Shown below is the method to mount multiple assemblies.

## Typical Mounting Bar Lengths & Mounting Holes Tabulation



Magnetic Coil Type	Number of Rows N	Spacing Bet. Holes C (mm)	Mounting Bar Length L (mm)	S (mm)
ICHXX-030	2	16.0	30	7.0
ICHXX-050	2	36.0	50	7.0
ICHXX-075	3	32.0	75	5.5
ICHXX-100	3	36.0	100	14.0
ICHXX-150	5	32.0	150	11.0
ICHXX-200	6	36.0	200	10.0
ICHXX-250	8	32.0	250	13

\* Note: Flatness and height of magnet ways is defined at fastened to the flat base.

# IL06 Performance Data

## Ironless Non-Cooled Motors Series

Rated Performance	Symbol	Units	IL06-030		IL06-050		IL06-075		IL06-100	
Peak Force	Fp	N	120		200		300		400	
Continuous Force @ Tmax (1)	Fc	N	30.3		49.7		67.6		82.8	
Motor Constant	Km	N√W	5.6		8.0		10.2		12.1	
Electrical Specifications (2)										
		Winding Code	A1	A4	A1	A4	A1	A4	A1	A4
Peak Current	Ip	Arms	7.1	14.2	7.0	14.0	7.0	14.0	7.0	14.0
Continuous Current @Tmax	Ic	Arms	1.8	3.6	1.7	3.5	1.6	3.2	1.5	2.9
Electrical Resistance @ 25°C±10%	Rm	Ohms L-L	6.1	1.5	8.6	2.2	11.7	2.9	14.7	3.7
Electrical Inductance ±20%	L	mH L-L	1.3	0.33	3.00	0.75	5.00	1.25	7.00	1.75
Back EMF Constant @ 25°C±10%	Ke	Vpeak/m/s L-L	13.7	6.9	23.3	11.6	34.9	17.5	46.5	23.3
Force Constant @ 25°C±10%	kf	N/Arms	16.8	8.4	28.5	14.3	42.8	21.4	57.0	28.5
Mechanical Specifications										
Coil Assembly Mass ±15%	Mc	kg	0.27		0.32		0.38		0.45	
Magnetic Way Type			MW		MW		MW075		MW075	
			030	030L	050	050L				
Magnetic Way Mass ±15%	Mw	kg/m	9.4	7.3	12.2	10.2	18.9		27.3	
Figures of Merit and Additional Data										
Electrical Time Constant	Te	ms	0.21		0.35		0.43		0.48	
Max.Theoretical Acceleration (3)	Amax	m/s²	45.2		63.6		80.6		90.7	
Magnetic Attraction	Fa	kN	0		0		0		0	
Thermal Resistance (4) (Coils to External Structure)	Rth	°C/Watt	1.61		1.26		1.04		0.87	
Max. Allowable Coil Temp. (4)	Tmax	°C	130		130		130		130	

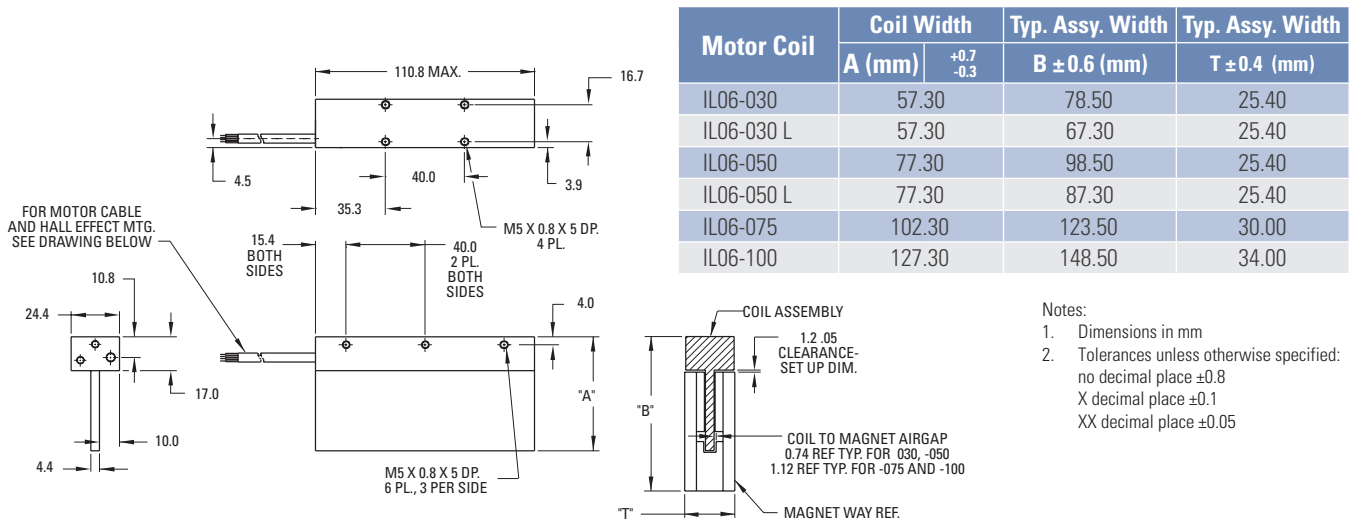
### Notes:

1. The motor continuous rated force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings can be made available. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.

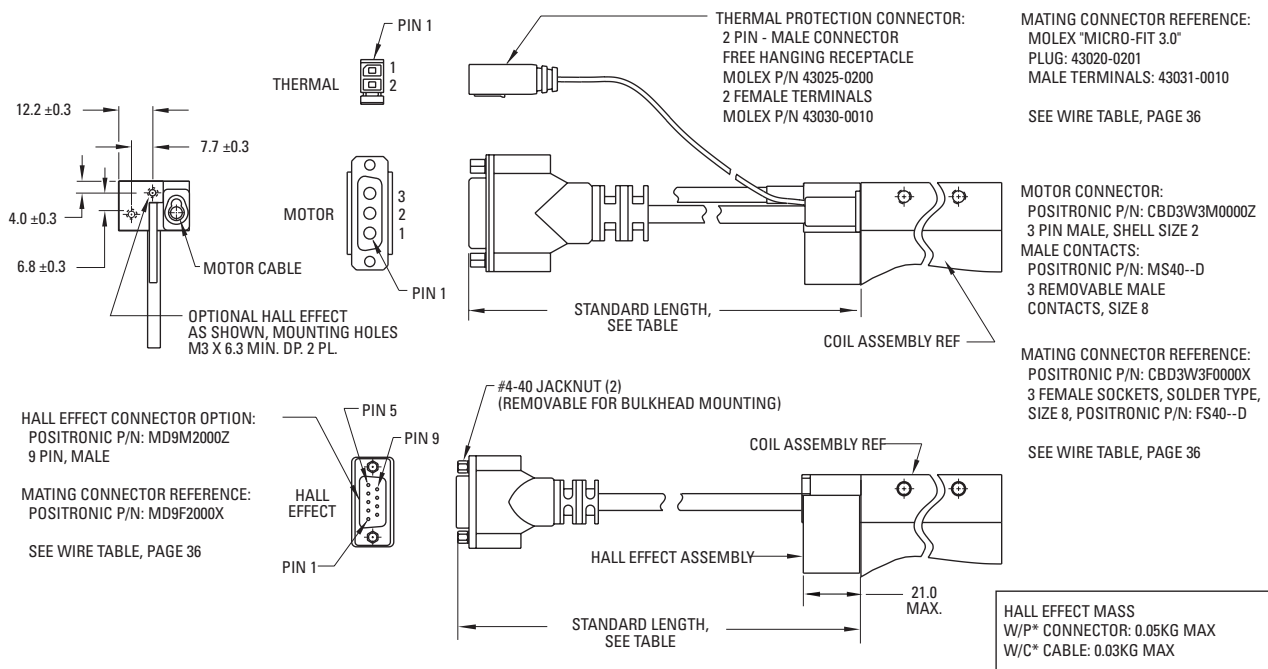


# IL06 Outline Drawings

## Ironless Non-Cooled Motors Series



## Termination and Hall Effect Options



Connector Option	
Connector	Cable Length (mm)
P1	400
P2	200
P3	100
P4	1200

Flying Lead Option	
Leads	Cable Length (mm)
C1	400
C2	200
C3	100
C4	1200

# IL12 Performance Data

## Ironless Non-Cooled Motors Series

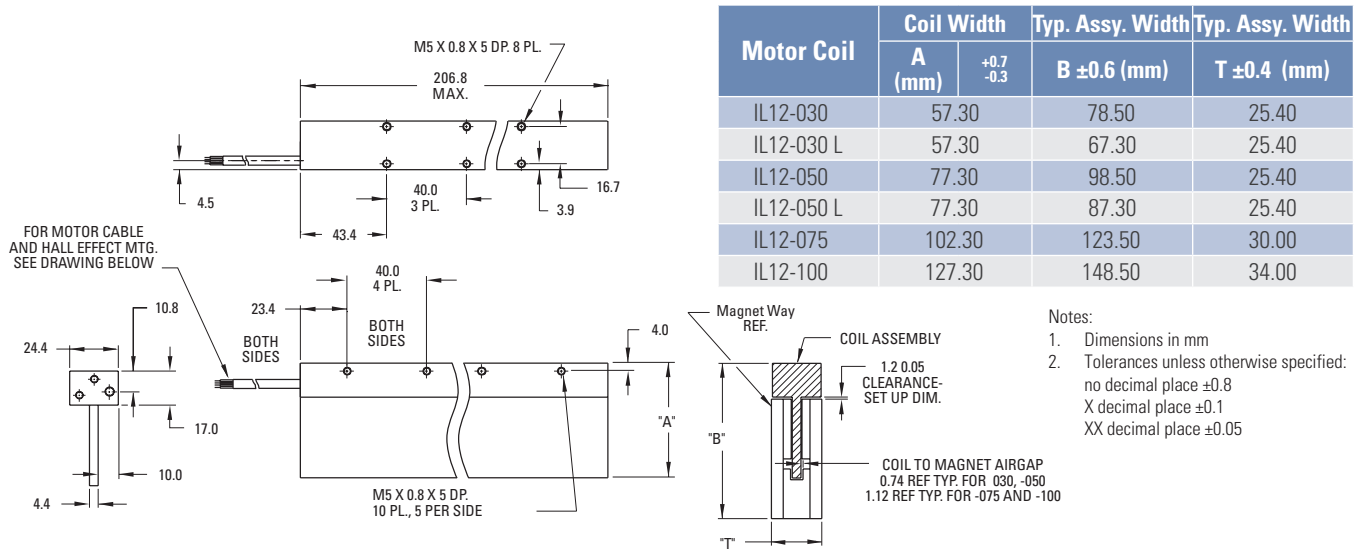
Rated Performance	Symbol	Units	IL12-030			IL12-050			IL12-075			IL12-100	
Peak Force	Fp	N	240			400			600			800	
Continuous Force @ Tmax (1)	Fc	N	62.1			88.4			119			148	
Motor Constant @ 25°C	Km	N√W	7.8			11.3			14.5			17.2	
Electrical Specifications (2)													
		Winding Code	A1	A2	A4	A1	A2	A4	A1	A2	A4	A2	A4
Peak Current	Ip	Arms	7.1	14.2	28.5	7.0	14.0	28.1	7.0	14.0	28.1	14.0	28.1
Continuous Current @Tmax	Ic	Arms	1.8	3.7	7.4	1.6	3.1	6.2	1.4	2.8	5.6	2.6	5.2
Electrical Resistance @ 25°C±10%	Rm	Ohms L-L	12.2	3.1	0.8	17.2	4.3	1.1	23.3	5.8	1.5	7.4	1.8
Electrical Inductance ±20%	L	mH L-L	2.60	0.65	0.16	6.00	1.5	0.38	10.0	2.5	0.63	3.5	0.88
Back EMF Constant @ 25°C±10%	Ke	Vpeak/m/s L-L	27.5	13.8	6.9	46.5	23.3	11.6	69.8	34.9	17.5	46.5	23.3
Force Constant @ 25°C±10%	Kf	N/Arms	33.7	16.9	8.4	57.0	28.5	14.3	85.5	42.8	21.4	57.0	28.5
Mechanical Specifications													
Coil Assembly Mass ±15%	Mc	kg	0.42			0.52			0.65			0.77	
Magnetic Way Type			MW			MW			MW075			MW100	
			030	030L		050	050L						
Magnetic Way Mass ±15%	Mw	kg/m	9.4	7.3		12.2	10.2		18.9			27.3	
Figures of Merit and Additional Data													
Electrical Time Constant	Te	ms	0.21			0.35			0.43			0.48	
Max.Theoretical Acceleration (3)	Amax	m/s²	58.2			78.4			94.1			106	
Magnetic Attraction	Fa	kN	0			0			0			0	
Thermal Resistance (4) (coils to external structure)	Rth	°C/Watt	0.804			0.629			0.519			0.433	
Max. Allowable Coil Temp. (4)	Tmax	°C	130			130			130			130	

### Notes:

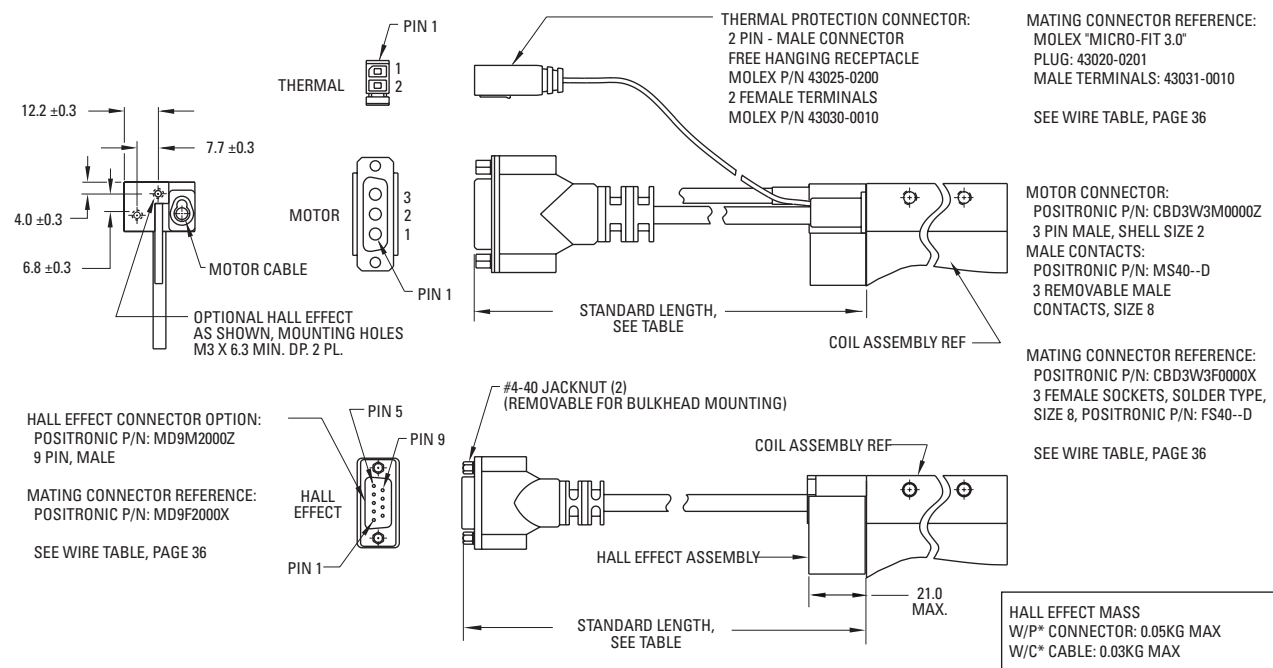
1. The motor continuous rated force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings can be made available. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.

# IL12 Outline Drawings

## Ironless Non-Cooled Motors Series



## Termination and Hall Effect Options



Connector Option	
Connector	Cable Length (mm)
P1	400
P2	200
P3	100
P4	1200

Flying Lead Option	
Leads	Cable Length (mm)
C1	400
C2	200
C3	100
C4	1200

# IL18 Performance Data

## Ironless Non-Cooled Motors Series

Rated Performance	Symbol	Units	IL18-030				IL18-050			
Peak Force	Fp	N	360				600			
Continuous Force @ Tmax (1)	Fc	N	92.1				131			
Motor Constant @ 25°C	Km	N√W	9.7				13.8			
Electrical Specifications (2)										
		Winding Code	A1	A2	A3	A4	A1	A2	A3	A4
Peak Current	Ip	Arms	7.1	14.3	21.4	42.8	7.0	14.0	21.0	42.1
Continuous Current @Tmax	Ic	Arms	1.8	3.6	5.5	11.0	1.5	3.1	4.6	9.2
Electrical Resistance @ 25°C±10%	Rm	Ohms L-L	18.2	4.6	2.0	0.5	25.7	6.4	2.9	0.7
Electrical Inductance ±20%	L	mH L-L	3.8	0.95	0.42	0.11	9.00	2.25	1.00	0.25
Back EMF Constant @ 25°C±10%	Ke	Vpeak/m/s L-L	41.2	20.6	13.7	6.9	69.8	34.9	23.3	11.6
Force Constant @ 25°C±10%	Kf	N/Arms	50.5	25.3	16.8	8.4	85.5	42.8	28.5	14.3
Mechanical Specifications (2)										
Coil Assembly Mass ±15%	Mc	kg	0.57				0.72			
Magnetic Way Type			MW				MW			
			030	030L		050	050L			
Magnetic Way Mass ±15%	Mw	kg/m	9.4	7.3		12.2	10.2			
Figures of Merit and Additional Data										
Electrical Time Constant	Te	ms	0.21				0.35			
Max.Theoretical Acceleration (3)	Amax	m/s²	64.5				84.9			
Magnetic Attraction	Fa	kN	0				0			
Thermal Resistance (4) (coils to external structure)	Rth	°C/Watt	0.536				0.419			
Max. Allowable Coil Temp. (4)	Tmax	°C	130				130			

### Notes:

1. The motor continuous rated force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings can be made available. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.

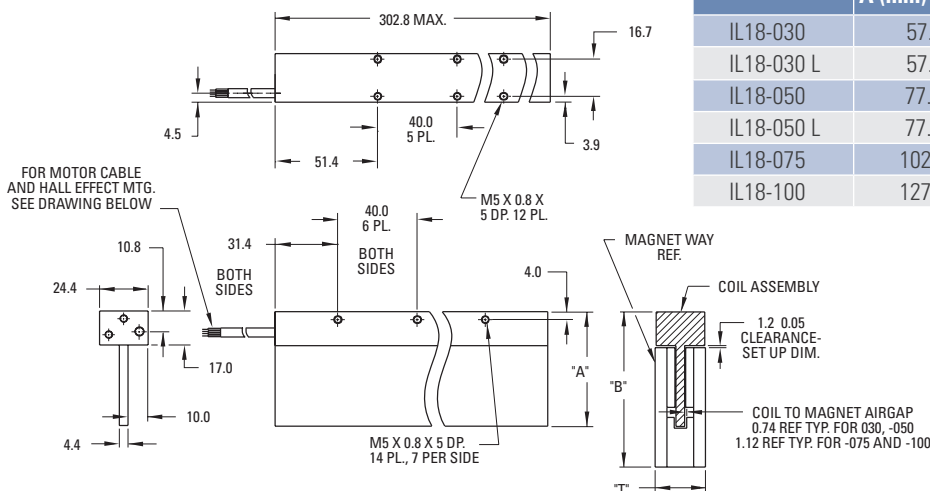
Rated Performance	Symbol	Units	IL18-075				IL18-100			
Peak Force	Fp	N	900				1200			
Continuous Force @ Tmax (1)	Fc	N	173				211			
Motor Constant @ 25°C	Km	N√W	17.7				21.0			
Electrical Specifications (2)										
		Winding Code	A1	A2	A3	A4	A1	A2	A3	A4
Peak Current	Ip	Arms	7.0	14.0	21.0	42.1	7.0	14.0	21.0	42.1
Continuous Current @Tmax	Ic	Arms	1.4	2.7	4.0	8.1	1.2	2.5	3.7	7.4
Electrical Resistance @ 25°C±10%	Rm	Ohms L-L	35.0	8.8	3.9	1.0	44.2	11.1	4.9	1.2
Electrical Inductance ±20%	L	mH L-L	15.0	3.75	1.67	0.42	21.0	5.25	2.33	0.58
Back EMF Constant @ 25°C±10%	Ke	Vpeak/m/s L-L	105	52.4	34.9	17.5	140	69.9	46.6	23.3
Force Constant @ 25°C±10%	Kf	N/Arms	128	64.2	42.8	21.4	171	85.6	57.0	28.5
Mechanical Specifications										
Coil Assembly Mass ±15%	Mc	kg	0.91				1.10			
Magnetic Way Type			MW075				MW100			
Magnetic Way Mass ±15%	Mw	kg/m	18.9				27.3			
Figures of Merit and Additional Data										
Electrical Time Constant	Te	ms	0.43				0.48			
Max.Theoretical Acceleration (3)	Amax	m/s²	101				111			
Magnetic Attraction	Fa	kN	0				0			
Thermal Resistance (4) (coils to external structure)	Rth	°C/Watt	0.35				0.29			
Max. Allowable Coil Temp. (4)	Tmax	°C	130				130			

## Notes:

1. The motor continuous rated force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings can be made available. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.

# IL18 Outline Drawings

## Ironless Non-Cooled Motors Series

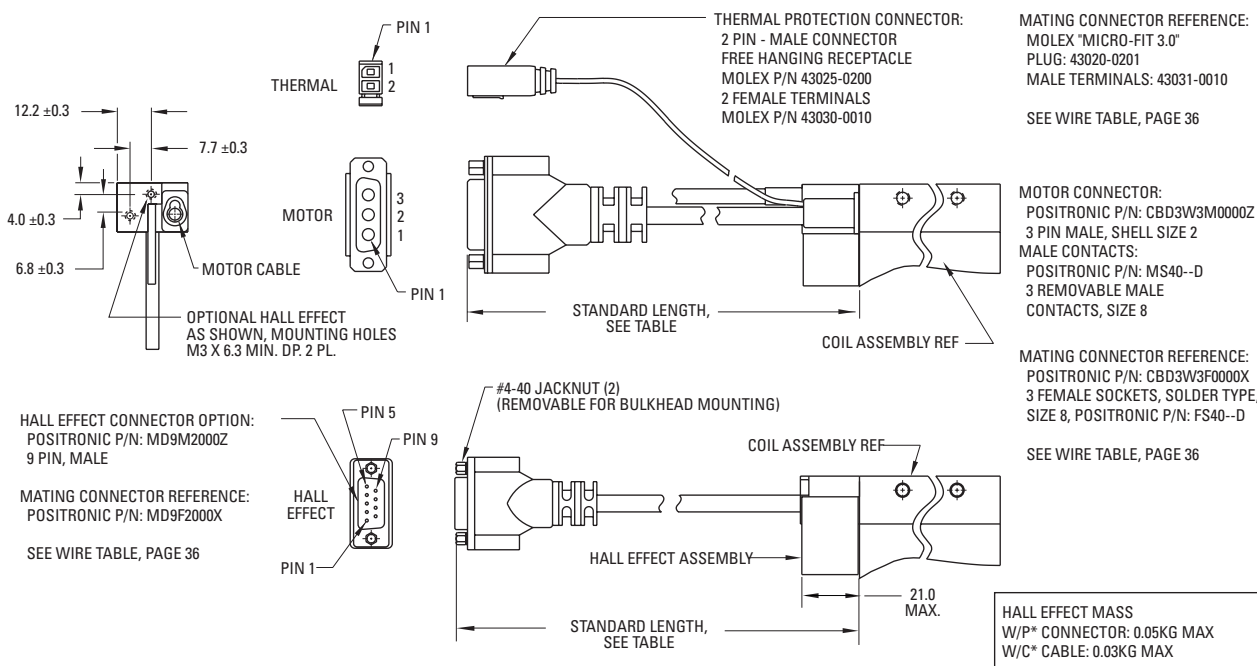


Motor Coil	Coil Width		Typ. Assy. Width	Typ. Assy. Width
	A (mm)	$\pm 0.7$ $-0.3$	B $\pm 0.6$ (mm)	T $\pm 0.4$ (mm)
IL18-030	57.30		78.50	25.40
IL18-030 L	57.30		67.30	25.40
IL18-050	77.30		98.50	25.40
IL18-050 L	77.30		87.30	25.40
IL18-075	102.30		123.50	30.00
IL18-100	127.30		148.50	34.00

### Notes:

1. Dimensions in mm
2. Tolerances unless otherwise specified:  
no decimal place  $\pm 0.8$   
X decimal place  $\pm 0.1$   
XX decimal place  $\pm 0.05$

## Termination and Hall Effect Options



Connector Option	
Connector	Length (mm)
P1	400
P2	200
P3	100
P4	1200

Flying Lead Option	
Leads	Length (mm)
C1	400
C2	200
C3	100
C4	1200

## Notes



# IL24 Performance Data

## Ironless Non-Cooled Motors Series

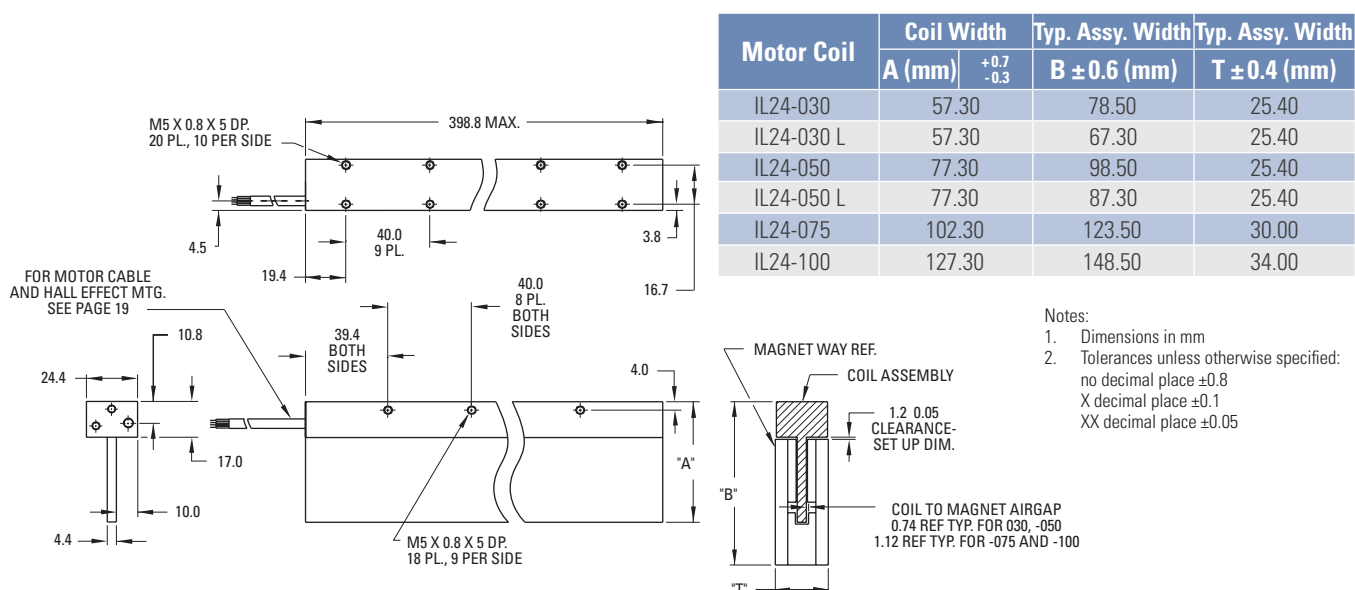
Rated Performance	Symbol	Units	IL24-030			IL24-050			IL24-075				IL24-100			
Peak Force	Fp	N	480			800			1200				1600			
Continuous Force @ Tmax (1)	Fc	N	109			155			211				262			
Motor Constant @ 25°C	Km	N√W	11.2			15.9			20.6				24.4			
Electrical Specifications (2)																
		Winding Code	A1	A2	A3	A1	A2	A3	A1	A2	A3	A4	A1	A2	A3	A4
Peak Current	Ip	Arms	7.1	14.2	28.5	7.0	14.0	28.1	7.0	14.0	28.0	56.1	7.0	14.0	28.1	56.1
Continuous Current @Tmax	Ic	Arms	1.6	3.2	6.4	1.4	2.7	5.4	1.2	2.5	4.9	9.9	1.2	2.3	4.6	9.2
Electrical Resistance @ 25°C±10%	Rm	Ohms L-L	24.3	6.1	1.5	34.3	8.6	2.1	46.6	11.7	2.9	0.73	58.9	14.7	3.7	0.92
Electrical Inductance ±20%	L	mH L-L	5.1	1.28	0.32	12.0	3.00	0.75	20.0	5.0	1.25	0.31	28.0	7.00	1.75	0.44
Back EMF Constant @ 25°C±10%	Ke	Vpeak/m/s L-L	55.0	27.5	13.8	93.1	46.5	23.3	140.	69.9	34.9	17.5	186	93.1	46.6	23.3
Force Constant @ 25°C±10%ww	Kf	N/Arms	67.4	33.7	16.9	114	57.0	28.5	171	85.6	42.8	21.4	228	114	57.0	28.5
		lbf/Arms	15.2	7.6	3.8	25.6	12.8	6.4	38.5	19.2	9.6	4.8	51.3	25.6	12.8	6.4
Mechanical Specifications																
Coil Assembly Mass ±15%	Mc	kg	0.72			0.92			1.17				1.42			
Magnetic Way Type			MW			MW			MW				MW			
			030	030L	050	050L	075				100					
Magnetic Way Mass ±15%	Mw	kg/m	9.4	7.3	12.2	10.2	18.9				27.3					
Figures of Merit and Additional Data																
Electrical Time Constant	Te	ms	0.21			0.35			0.43				0.48			
Max.Theoretical Acceleration(3)	Amax	m/s²	68.0			88.7			105				115			
Magnetic Attraction	Fa	kN	0			0			0				0			
Thermal Resistance (4) (coils to external structure)	Rth	°C/Watt	0.40			0.32			0.26				0.22			
Max. Allowable Coil Temp. (4)	Tmax	°C	130			130			130				130			

### Notes:

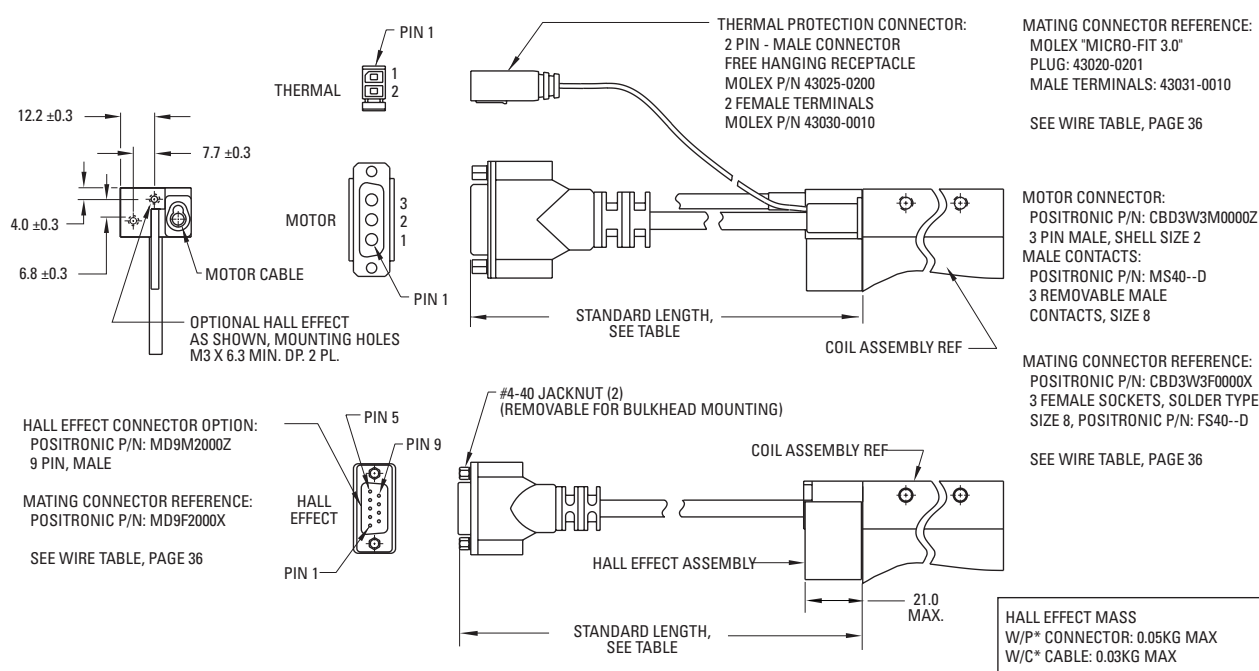
1. The motor continuous rated force is measured with the motor coils achieving the motor maximum allowable temperature Tmax.
2. Alternate windings can be made available. Please consult the Kollmorgen Customer Support for design options.
3. Maximum theoretical acceleration is based on the motors peak force and the motor mass alone. Limitations due to such factors as the additional mass of the load, the bearing type and design, the shock rating of the feedback, the peak current available from the amplifier etc. must be considered to determine the achievable acceleration in each application.
4. Please see our application sizing pages in the back of this guide for more details on sizing and thermal considerations.

# IL24 Outline Drawings

## Ironless Non-Cooled Motors Series



## Termination and Hall Effect Options

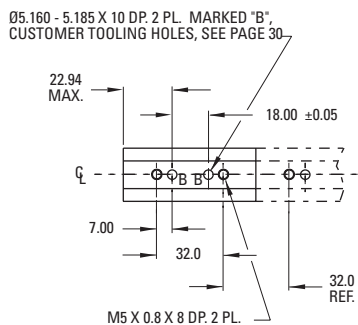
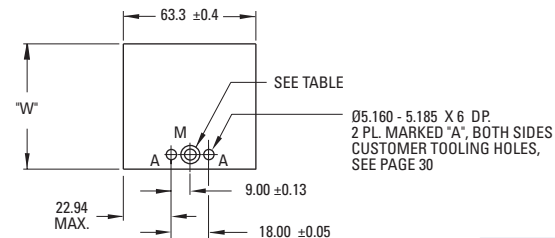


Connector Option	
Connector	Cable Length (mm)
P1	400
P2	200
P3	100
P4	1200

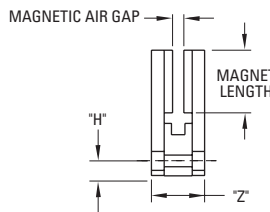
Flying Lead Option	
Leads	Cable Length (mm)
C1	400
C2	200
C3	100
C4	1200

# Ironless Magnet Ways

## MWxxx-0064



Magnet assemblies are modular and can be installed in multiples of same or alternate lengths (see page 34). Standard assembly lengths are shown below.

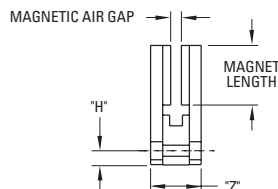
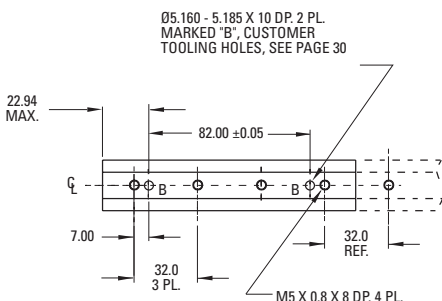
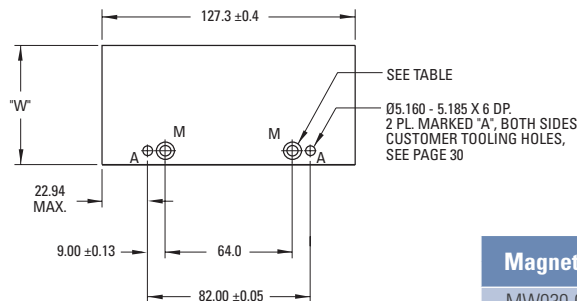


- Notes:
1. Dimensions in mm
  2. Tolerances unless otherwise specified:  
no decimal place  $\pm 0.8$   
X decimal place  $\pm 0.1$   
XX decimal place  $\pm 0.05$

Magnet Way	Magnet Size Ref.	H $\pm 0.8$	W $\pm 0.4$	Z $\pm 0.4$
MW030-0064	30 mm	7.11	60.20	25.40
MW030L-0064	30 mm	5.69	49.00	25.40
MW050-0064	50 mm	7.11	80.20	25.40
MW050L-0064	50 mm	5.69	69.00	25.40
MW075-0064	75 mm	8.23	105.20	30.00
MW100-0064	100 mm	8.23	130.20	34.00

Magnet Way	Hardware (Hex. Socket Head Cap)					
	Hole Dia. $\pm 0.13$	C'bore Dia. $\pm 0.13$	Cbore Depth $\pm 0.13$	Metric	Inch	Bottom Mount Thread Option
MW030-0064	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW030L-0064	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW050-0064	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW050L-0064	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW075-0064	5.70	9.35	7.95	M5	#10	M5 X 0.8 X 8.0 DP.
MW100-0064	5.70	9.35	9.96	M5	#10	M5 X 0.8 X 8.0 DP.

## MWxxx-0128

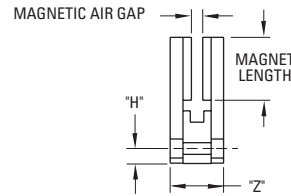
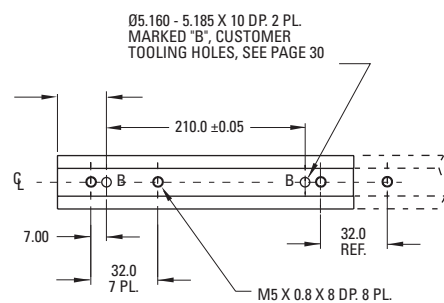
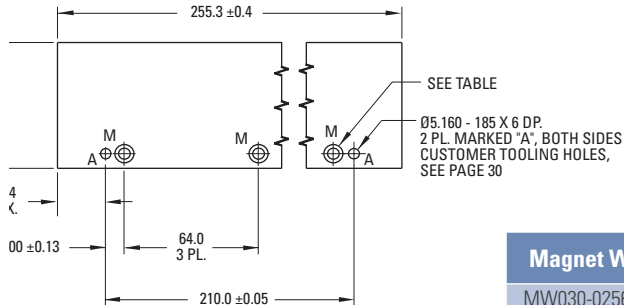


Magnet Way	Magnet Size Ref.	H $\pm 0.8$	W $\pm 0.4$	Z $\pm 0.4$
MW030-0128	30 mm	7.11	60.20	25.40
MW030L-0128	30 mm	5.69	49.00	25.40
MW050-0128	50 mm	7.11	80.20	25.40
MW050L-0128	50 mm	5.69	69.00	25.40
MW075-0128	75 mm	8.23	105.20	30.00
MW100-0128	100 mm	8.23	130.20	34.00

Magnet Way	Hardware (Hex. Socket Head Cap)					
	Hole Dia. $\pm 0.13$	C'bore Dia. $\pm 0.13$	Cbore Depth $\pm 0.13$	Metric	Inch	Bottom Mount Thread Option
MW030-0128	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW030L-0128	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW050-0128	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW050L-0128	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW075-0128	5.70	9.35	7.95	M5	#10	M5 X 0.8 X 8.0 DP.
MW100-0128	5.70	9.35	9.96	M5	#10	M5 X 0.8 X 8.0 DP.

**MWxxx-0256**

Magnet assemblies are modular and can be installed in multiples of same or alternate lengths (see page 32). Standard assembly lengths are shown below.

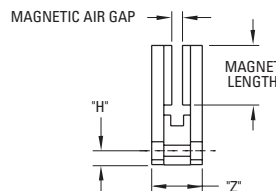
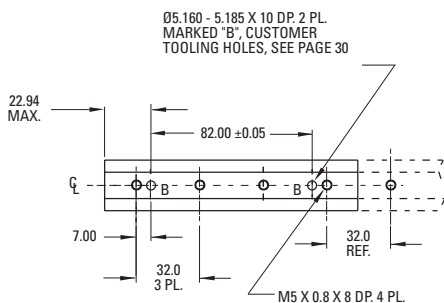
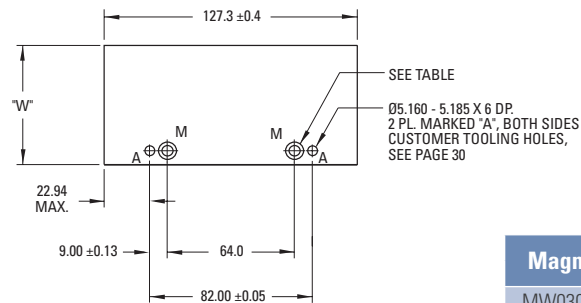


Notes:

1. Dimensions in mm (inches)
2. Tolerances unless otherwise specified:  
no decimal place ±0.8 (0.3)  
X decimal place ±0.1 (.004)  
XX decimal place ±0.05 (0.002)

Magnet Way	Magnet Size Ref.	H ±0.8	W ±0.4	Z ±0.4
MW030-0256	30 mm	7.11	60.20	25.40
MW030L-0256	30 mm	5.69	49.00	25.40
MW050-0256	50 mm	7.11	80.20	25.40
MW050L-0256	50 mm	5.69	69.00	25.40
MW075-0256	75 mm	8.23	105.20	30.00
MW100-0256	100 mm	8.23	130.20	34.00

Magnet Way	Hardware (Hex. Socket Head Cap)					Bottom Mount Thread Option
	Hole Dia. ±0.13	C'bore Dia. ±0.13	Cbore Depth ±0.13	Metric	Inch	
MW030-0512	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW030L-0512	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW050-0512	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW050L-0512	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW075-0512	5.70	9.35	7.95	M5	#10	M5 X 0.8 X 8.0 DP.
MW100-0512	5.70	9.35	9.96	M5	#10	M5 X 0.8 X 8.0 DP.

**MWxxx-0512**

Magnet Way	Magnet Size Ref.	H ±0.8	W ±0.4	Z ±0.4
MW030-0512	30 mm	7.11	60.20	25.40
MW030L-0512	30 mm	5.69	49.00	25.40
MW050-0512	50 mm	7.11	80.20	25.40
MW050L-0512	50 mm	5.69	69.00	25.40
MW075-0512	75 mm	8.23	105.20	30.00
MW100-0512	100 mm	8.23	130.20	34.00

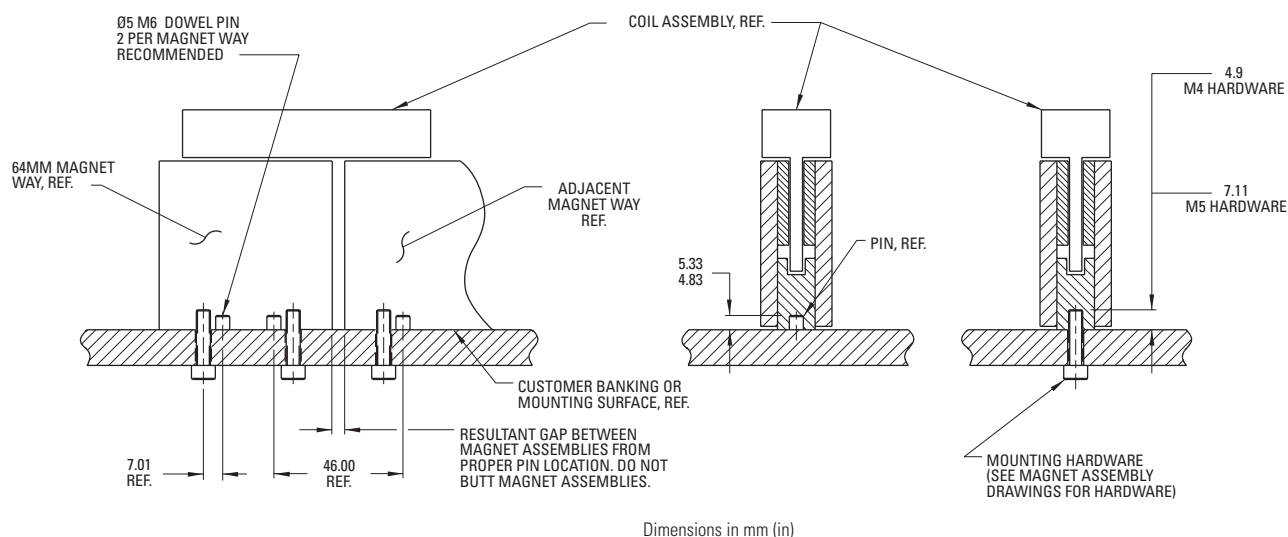
Magnet Way	Hardware (Hex. Socket Head Cap)					Bottom Mount Thread Option
	Hole Dia. ±0.13	C'bore Dia. ±0.13	Cbore Depth ±0.13	Metric	Inch	
MW030-0512	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW030L-0512	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW050-0512	5.70	9.35	5.79	M5	#10	M5 X 0.8 X 8.0 DP.
MW050L-0512	4.70	7.80	5.79	M4	#8	M4 X 0.7 X 6.0 DP.
MW075-0512	5.70	9.35	7.95	M5	#10	M5 X 0.8 X 8.0 DP.
MW100-0512	5.70	9.35	9.96	M5	#10	M5 X 0.8 X 8.0 DP.

# Ironless Magnet Ways

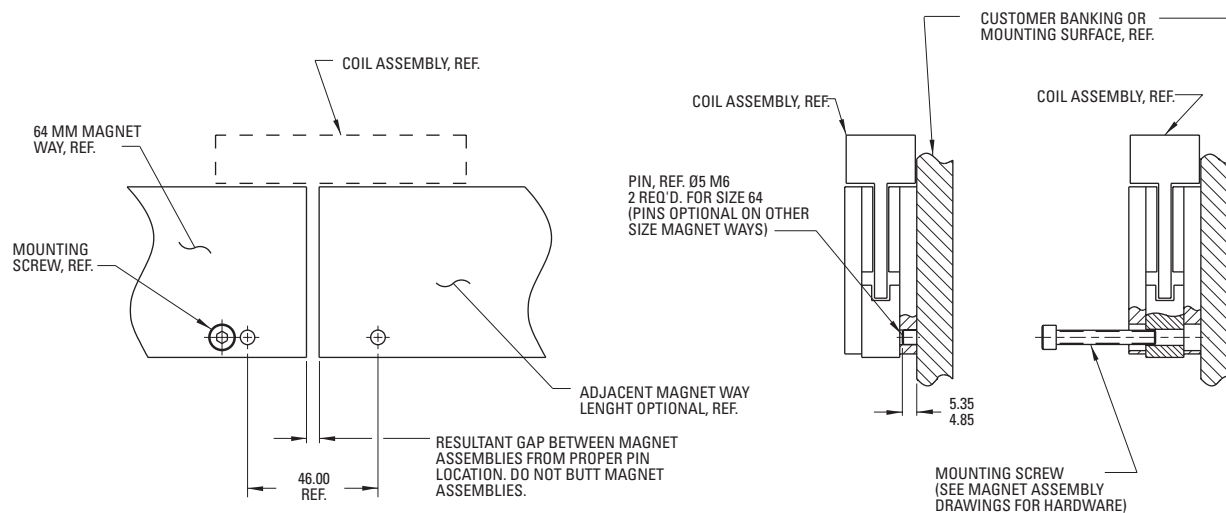
Magnet Way widths correspond to the mating coil assembly width.

Magnet Way assemblies are modular and come in standard lengths: 64. 128. 256. 512 mm.

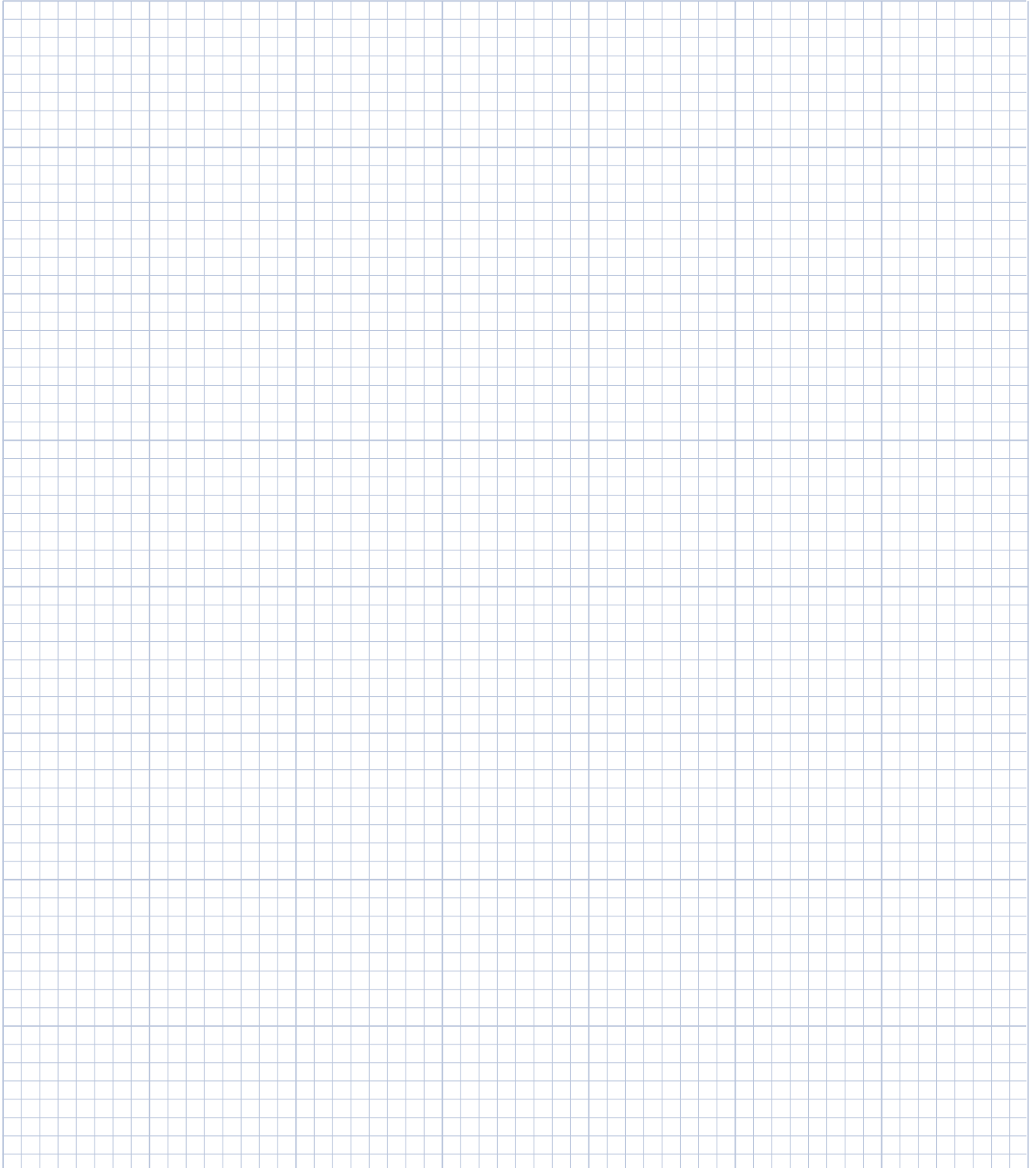
## Bottom Mounting Installation



## Side mounting installation



# Notes



# Wiring and Output

## Ironcore Non-Cooled Motors ICH-Series

### Motor Wire Table

See the cable data on pages 13, 15, 17, 19

	Cable 0.75 mm <sup>2</sup> 1)	Cable > 0.75 mm <sup>2</sup>	Plug BKUA Option 1)
U	Black 1	Black 1	1
V	Black 2	Black 2	3
W	Black 3	Black 3	4
PE	Green/Yellow	Green/Yellow	PE
PTC1	Yellow	Black 5	A
PTC2	Green	Black 6	B
KTY+	White	Black 7	C
KTY-	Brown	Black 8	D

Note 1: For motors with  $I_c < 15$  A

### Hall Effect Wire Table

Ø 4.6 mm

Pin Number	Color	Function
1	Gray	+5 VDC
2	Green	S1
3	Yellow	S2
4	Brown	S3
5	White	Return
Shell	Shield	Shield

## Ironless Non-Cooled Motors IL-Series

### Motor Wire Table

A1, A2, A3, A4: 18 AWG, Ø 5.6 mm

Pin Number	Color	Function
1	Red	A
2	White	B
3	Black	C
Connector Shell	Green/Yellow	GND
Connector Shell	Violet	Shield

### Thermal Protection Wire Table

26 AWG, Ø 3.8 mm

Pin	Color	Transition Point
1	Black/White	130°C
2	Black/White	130°C

Note: TIC-X extender cable is shielded

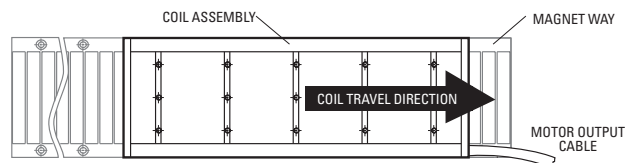
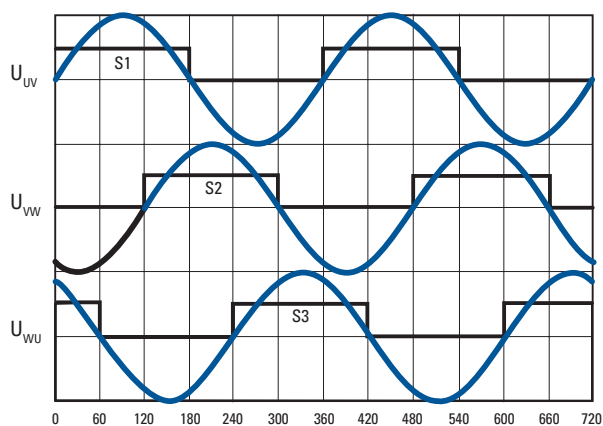
### Hall Effect Wire Table

26 AWG, Ø 6.0 mm

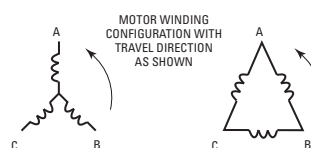
Pin Number	Color	Function
1	Gray	+5 VDC
2	Green	S1
3	Yellow	S2
4	Brown	S3
5	White	Return
Shell	Shield	Shield



## Ironcore and Ironless Motors Output Diagrams



Magnet pole pitch:  
Both Ironcore (ICH) and Ironless (IL) feature the same pole pitch, which is 32 mm (360 electrical degrees).

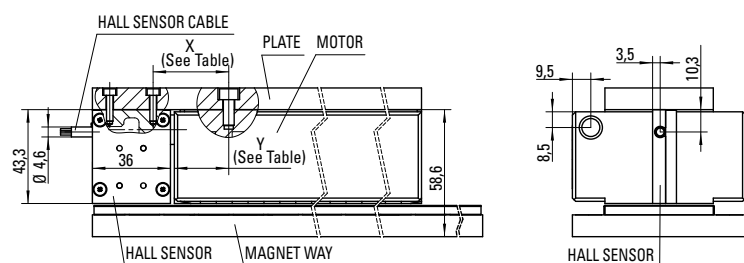


Motor BEMF phases U, V, W relative to Hall effect devices S1,S2,S3 with coil travel direction towards the motor output cable assembly exit as shown on the right hand side

Note:

1. The diagram above refers to both ironless (IL) and ironcore (ICH) motors

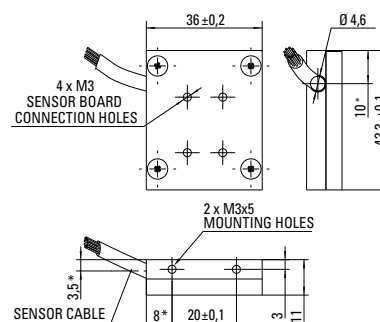
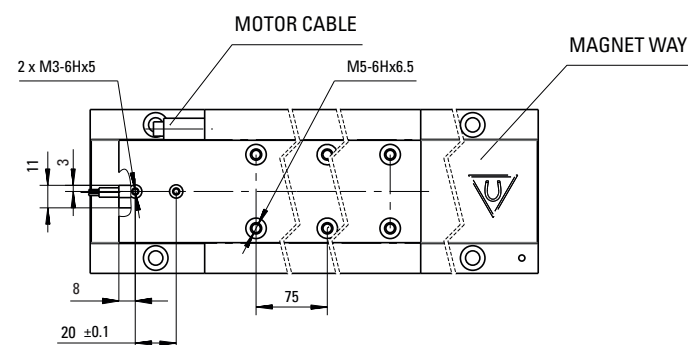
## Mounting of Hall Sensor on ICH Ironcore Motors



Hall Sensor Mounting Distance X

ICH Type	X (mm)	Y (mm)
ICH11	34.9	25.1
ICH22	48.9	38.1
ICH33	60.9	51.1
ICH44	36.4	26.6

Dimensions Hall Sensor  
HD-Y-Px or HD-D-Px (mm)



\* - for reference only

# Application Sizing

## To size a Linear Motor, you will need to:

1. Define a Move Profile
2. Define the Load
3. Size the Motor and the Amplifier

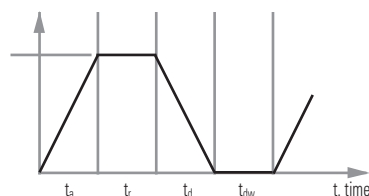
From the move profile, we can calculate the maximum speed and the maximum acceleration/deceleration. From the load we can calculate all of the forces at constant speed and using the move profile all the dynamic forces during acceleration and deceleration. Once a motor is selected, the weight of the moving parts of the motor are added to the moving weight to calculate a total Peak Force and a total RMS force. The motor should be able to deliver the peak force and the calculated RMS force should be less than the motor continuous force to ensure a known safety margin. The coil temperature rise can also be calculated to ensure that it is lower than the intended maximum temperature rise.

The maximum bus voltage and continuous and peak current can also be calculated and compared to the selected amplifier to be sure the calculated performances can be achieved.

## 1. Move Profile

### Triangular/Trapezoidal

V, Velocity



Units  
**SI**

$S_m$ - Move displacement	meters
$t_a$ - Acceleration Time	seconds
$t_r$ - Time run at constant speed	seconds
$t_d$ - Deceleration Time	seconds
$t_{dw}$ - Dwell Time	seconds
$V_m$ - Max Velocity	meter
$A_m$ - Acceleration	meter/sec <sup>2</sup>
$D_m$ - Deceleration	meter/sec <sup>2</sup>

## Example:

Move 0.1 meter in 100 msec assuming  $t_a = t_d$  and  $t_r = 0$ .  
(assume triangular move)

**Max Speed:**

$$V_m = 2 \cdot S_m / (t_a + t_d + 2 \cdot t_r)$$

$$V_m = 2 \cdot 0.1 / (100E-3) \text{ m/s}$$

$$= 2 \text{ m/s}$$

## Max Acceleration/Deceleration

Acceleration

$$A_m = V_m / t_a$$

$$A_m = 2 / 50E-3 \text{ m/s}^2$$

$$= 40 \text{ m/s}^2$$

$$A_m \text{ "g"} = A_m / 9.81 \text{ m/s}^2$$

$$a \text{ (g)} = 40 / 9.81$$

$$= 4.08 \text{ g}$$

Deceleration

$$D_m = V_m / t_d$$

$$D_m = 2 / 50E-3 \text{ m/s}^2$$

$$= 40 \text{ m/s}^2$$

$$D_m \text{ "g"} = D_m / 9.81 \text{ m/s}^2$$

$$d \text{ (g)} = 40 / 9.81$$

$$= 4.08 \text{ g}$$

## 2. Load

Units

	<b>SI</b>
$F_{ext}$ - External Force only (Cutting force, etc.)	N
$F_{acc}$ - Acceleration Force only	N
$F_r$ - Run Force at constant speed	N
$F_{dec}$ - Deceleration Force only	N
$F_{am}$ - Max. Acceleration Force	N
$F_{dm}$ - Max. Deceleration Force	N
$F_{dw}$ - Dwell Force	N
$F_{rms}$ - RMS Force	N
$\omega$ - Coefficient of Friction (bearing support)	—
$M_l$ - Load Mass	kg
$M_c$ - Coil Mass	kg
$M_{cb}$ - Counterbalance Mass	kg
$F_a$ - Magnetic Attraction Force	N
CB - Counterbalance of load in %	—
$q$ - Angle of Linear Displacement with horizontal (0° = horizontal, 90° vertical)	degrees
$g$ - Gravity coefficient	9.81 m/s <sup>2</sup>
$n$ - Number of motors in parallel	—

## BASIC FORMULAS\*:

We assume a general case where we have n motors solidly coupled pushing the load and a possible counterbalance weight M<sub>cb</sub> (Mostly for vertical displacement).

### Example of Coefficient of Friction $\mu$ :

Linear bearing w/ balls	0.002 - 0.004
Linear bearing w/ rollers	0.005
Steel on oiled steel	0.06
Steel on dry steel	0.2
Steel on concrete	0.3

### Counterbalance Weight:

$$M_{cb} = M_l \cdot CB/100$$

### Acceleration Force only:

$$F_{acc} = [(M_l / n) \cdot (1 + CB/100) + M_c] \cdot A_m$$

### Run Force at constant speed:

$$F_r = (M_l / n + M_c) \cdot g \cdot \sin(q) + m \cdot \cos(q) - (M_{cb}/n) \cdot g + F_a \cdot \mu + F_{ext}/n$$

### Deceleration Force only:

$$F_{dec} = [(M_l / n) \cdot (1 + CB/100) + M_c] \cdot D_m$$

### Maximum Acceleration Force:

$$F_{am} = F_{acc} + F_r$$

### Maximum Deceleration Force:

$$F_{dm} = F_{dec} - F_r$$

### Dwell Force:

$$F_{dw} = (M_l / n + M_c) \cdot g \cdot [\sin(q)] - (M_{cb}/n) \cdot g$$

RMS Force:

$$F_{rms} = \sqrt{\frac{F_{am}^2 \cdot t_a + F_r^2 \cdot t_r + F_{dm}^2 \cdot t_d + F_{dw}^2 \cdot t_{dw}}{t_a + t_r + t_d + t_{dw}}}$$

\* All calculations are given in SI units

## 3. SIZE THE MOTOR AND AMPLIFIER

### Example:

Moving Weight:	M <sub>l</sub> = 0.5 kg
Number of Motors:	n = 1
Horizontal Move:	q = 0
Counterbalance Force:	M <sub>cb</sub> = 0
External Force:	F <sub>ext</sub> = 0
Friction Coefficient:	m = 0.01

Assume same move as above with a Dwell Time of 50 ms.

$$\text{Run Force at Constant Speed: } F_r = 0.5 \cdot 9.81 \cdot 0.01 = 0.005 \text{ N}$$

$$\text{Acceleration Force only: } F_a = 0.5 \cdot 40 = 20 \text{ N}$$

$$\text{Deceleration Force only: } F_d = 0.5 \cdot 40 = 20 \text{ N}$$

$$\text{Maximum Accel Force: } F_{am} = 20 + 0.05 = 20.05 \text{ N}$$

$$\text{Maximum Decel Force: } F_{dm} = 20 - 0.05 = 19.95 \text{ N}$$

Rms Force:

$$F_{rms} = \sqrt{\frac{(20.05)^2 \cdot (50E-3) + (19.95)^2 \cdot (50E-3)}{100E-3 + 50E-3}}$$

$$F_{rms} = 16.3 \text{ N}$$

### Motor Sizing:

If we select an ironless motor for smoothest possible move we can use Motor IL060-30A1. This motor has a coil mass of 0.21 kg and no attractive force. By adding that weight in equations above, we need an additional force of  $0.21 \cdot 40 \cdot 0.01 = 0.084 \text{ N}$ .

So peak force is  $20.05 + 0.08 = 20.13 \text{ N}$  and RMS force is  $23.19 \text{ N}$ . This motor will have a safety factor of  $(38-23.19)/100/38 = 39\%$ .

### Sizing the Amplifier :

	SI Units
I <sub>a</sub> - Max Acceleration Current	A
I <sub>r</sub> - Run Current	A
I <sub>d</sub> - Max Deceleration Current	A
I <sub>dw</sub> - Dwell Current	A
I <sub>rms</sub> - RMS Current	A
K <sub>f</sub> - Force Constant	N/A
R <sub>m</sub> - Motor Electrical Resistance	Ohms L-L
K <sub>e</sub> - Back EMF Constant	Vpeak/m/s
V <sub>bus</sub> - Bus Voltage	V DC
L - Electrical Inductance	H L-L

$$\text{Max Acceleration Current: } I_a = F_{am} / K_f$$

$$\text{Run Current at constant Speed: } I_r = F_r / K_f$$

$$\text{Max Deceleration Current only: } I_d = F_{dm} / K_f$$

$$\text{Dwell Current: } I_{dw} = F_{dw} / K_f$$

$$\text{RMS Current: } I_{rms} = F_{rms} / K_f$$

# Application Sizing

## BUS VOLTAGE:

If we assume a sine wave drive with a phase advance  $\varphi$  (degrees) and full conduction, the minimum bus voltage (see Fig. 1) is:

$$V_{b1} = 2.4 \text{ V}$$

$$V_{b2} = K_e \cdot V_m$$

$$V_{b3} = \frac{\sqrt{3}}{\sqrt{2}} \cdot R_{m,hot} \cdot I_{rms}$$

$$V_{b4} = 2\pi \frac{\sqrt{3}}{\sqrt{2}} \cdot L \cdot I_{rms} \cdot V_m / \text{Pitch}$$

$$a_v = \arctan(V_{b4}/V_{b3})$$

$$V_{lr} = \sqrt{V_{b3}^2 + V_{b4}^2}$$

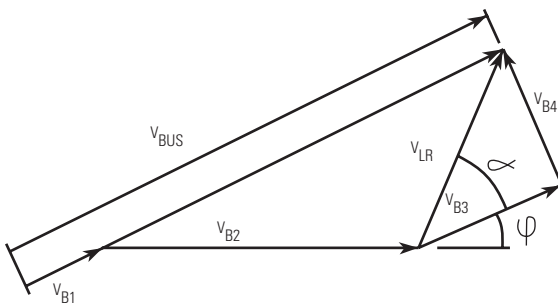
$$V_{bre} = V_{b2} + V_{lr} \cdot \cos(a_v + \varphi)$$

$$V_{bim} = V_{lr} \cdot \sin(a_v + \varphi)$$

$$V_{bus} = V_{b1} + \sqrt{V_{bre}^2 + V_{bim}^2}$$

Note: If there is no phase advance take  $\varphi = 0^\circ$

Figure 1:



## THERMAL CONSIDERATIONS:

Units

SI

$\Delta\theta$  - Coil increase of temperature

$^\circ\text{C}$

$R_{th}$  - Thermal Resistance

$^\circ\text{C}/\text{W}$

$K_m$  - Motor Constant

$\text{N}/\sqrt{\text{W}}$

$P_{out}$  - Output Power

$\text{W}$

### Coil Temperature rise

$$\Delta\theta = R_{th} \cdot (F_{rms}/K_m)^2$$

### Resistance of Coil hot (copper)

$$R_{m,hot} = \frac{R_{ambient} (234.5 + \theta_{hot})}{(234.5 + \theta_{amb})}$$

### Power Losses

$$P_{lrms} = \Delta\theta / R_{th} = \frac{(\theta_{hot} - \theta_{ambient})}{R_{th}}$$

### Output Power

$$P_{out(max)} = F_{am} \cdot V_m$$

### Example: In above example with:

$$R_{th} = 1.61 \text{ } ^\circ\text{C}/\text{W}$$

$$K_m = 4.7 \text{ N}/\sqrt{\text{W}}$$

### Coil Temperature rise:

$$\Delta\theta = 1.61 \cdot (23.19/4.7)^2 = 39.2^\circ\text{C}$$

$$\text{Power losses } P_l = 39.2 / 1.61 = 24.34 \text{ Watts}$$

$$\text{Max output Power } P_{out(max)} = 57 \text{ Watts}$$

### The Use of the Motor Constant $K_m$ :

Cognizance of the heat load being generated by the linear motor is an important consideration in the application of any linear motor. Linear motors are direct drive devices, typically mounted very close to the moving load. Therefore, any heat generated by the linear motor needs to be managed to avoid affecting the process or workpiece that the moving load is carrying. The motor constant  $K_m$  is a powerful parameter that can be used to determine this heat load,  $K_m$  equals:

$$K_m = \frac{F}{\sqrt{P_c}}$$

where the RMS force  $F$  is in Newtons,  
the RMS heat load  $P_c$  is in Watts  
and  $K_m$  is in units of  $\text{N}/\sqrt{\text{W}}$

The motor constant,  $K_m$ , allows us to determine motor performance capabilities such as shown in the following two examples. In the first example, we use  $K_m$  to calculate, for a given force, how many watts of generated heat are dissipated by the motor's coil assembly. In the second, we use  $K_m$  to determine the maximum RMS force developed by the motor when the dissipated power is limited to some value.

1. An application requires a continuous thrust force of 200 Newtons. The ICH11-050 ironcore motor is a good candidate, having a continuous force rating of 299 Newtons and a  $K_m$  of 38.0 N/√W. Therefore, since resistance rises 1.452 times at 145°C from the ambient value at 25°C, and since resistance is the square root denominator of  $K_m$ , we must write our equation as follows:

$$\text{Force} = \frac{K_m}{\sqrt{\text{Factor}}} \sqrt{\text{Power (dissipated)}}$$

$$200 = \frac{38.0}{\sqrt{1.452}} \sqrt{\text{Watts}}$$

$$\text{Power (dissipated)} = 40.2 \text{ Watts}$$

This value of watts is the power or heat generated by the motor.

2. The same application requires that no more than 20 watts are to be dissipated by the motor into the surrounding structure and environment. What is the maximum RMS force that the ICH11-050 motor may produce while not exceeding this power limit?

$$\text{Maximum RMS Force} = \frac{38.0}{\sqrt{1.452}} \sqrt{20} = 141 \text{ N}$$

Therefore, if the motor delivers no more than 141 N of thrust force on an RMS basis, then this same motor will not dissipate more than 20 watts.

## Continuous Force $F_c$ as a Function of Ambient Temperature

In our data sheets the continuous rated force  $F_c$  is the RMS force that the motor can supply continuously 100% of the time, assuming the ambient temperature is 25°C and with the coils achieving a maximum temperature of 130°C (IL series motors) respectively 145°C (ICH series motors). At higher or lower ambient temperatures, the  $F_c$  of the motor must be adjusted by a factor that is determined by the following equation:

$$\text{Factor} = \sqrt{\frac{(130 - \theta_{\text{Amb}})}{105}} \quad (\text{for IL series motors})$$

$$\text{Factor} = \sqrt{\frac{(145 - \theta_{\text{Amb}})}{120}} \quad (\text{for ICH series motors})$$

where  $\theta_{\text{Amb}}$  = Ambient Temperature in °C

**This factor vs. ambient temperature works out as:**

### ICH Ironcore Linear Motors

5°C	10°C	15°C	20°C	25°C	30°C	35°C	40°C	45°C
1.080	1.061	1.041	1.021	1.000	0.979	0.957	0.935	0.913

### IL Ironless Linear Motors

5°C	10°C	15°C	20°C	25°C	30°C	35°C	40°C	45°C
1.091	1.069	1.047	1.024	1.000	0.976	0.951	0.926	0.900

# Model Nomenclature

## Ironcore Types

**ICH 22 - 050 - A1 - TY - XX - 0**

### Coil Type

ICH = Ironcore High Voltage

### Coil Series

11 = 11 Series Ironcore  
22 = 22 Series Ironcore  
33 = 33 Series Ironcore  
44 = 44 Series Ironcore

### Coil Width (mm)

030 = 30 mm      150 = 150 mm  
050 = 50 mm      200 = 200 mm  
075 = 75 mm      250 = 250 mm  
100 = 100 mm

### Winding Code

A1: "Y"-Windings  
A5: "Δ" Windings

### Reserved for Customizations

00. 01. 02 .....

### Cable Option Px ( $I_c < 9$ A) or Cx

Px = Cable with Connector for motors with  $I_c < 9$  A  
Configuration (P1) includes 400 mm shielded cable with connector.  
P1 = 400 mm  
P2 = 200 mm  
P3 = 100 mm  
P4 = 1200 mm  
Cx = Motor cable and thermal cable with flying leads:  
C1 = 400 mm  
C2 = 200 mm  
C3 = 100 mm  
C4 = 1200 mm

### Thermal Protection

TY = Standard (both PTC and KTY)

## Magnetic Way Ironcore Types

**MCH 030 - 128 - 01**

### Magnet Way Type

MCH = Ironcore

### Magnet Way Width (mm)

030 = 30 mm      150 = 150 mm  
050 = 50 mm      200 = 200 mm  
075 = 75 mm      250 = 250 mm  
100 = 100 mm

### Customization

01 = Standard with stainless steel cover  
02. 03 .... Reserved

### Magnet Assembly Way Length (mm)

064 = 64 mm  
128 = 128 mm  
256 = 256 mm  
512 = 512 mm

## Hall Effect Assembly Ironcore Types

**HD - Y - Px**

### Hall Option

HD = Digital  
HA = Analog\*

### Winding Phase Connection

Y = Y (Star) Windings  
D = Δ (Triangle) Windings

### Cable Option

Px - Cable with Sub-D connector  
P1 = 400 mm  
P2 = 200 mm  
P3 = 100 mm  
P4 = 1200 mm

\* Under development

## Ironless Type

**IL 06 - 030 - A1 - TR - XX**

### Coil Type

IL = Ironless

### Coil Series

06 = 06 Series Ironless  
12 = 12 Series Ironless  
18 = 18 Series Ironless  
24 = 24 Series Ironless

### Magnetic Way Width (mm)

030 = 30 mm  
050 = 50 mm  
075 = 75 mm  
100 = 100 mm

### Winding Code

A1, A2, A3, A4: "Y"-Windings

### CableOption Px or Cx

Px = Cable with Connector:  
Configuration (P1) includes 400 mm shielded cable with connector.  
P1 = 400 mm  
P2 = 200 mm  
P3 = 100 mm  
P4 = 1200 mm  
Cx = Motor cable and thermal cable with flying leads:  
C1 = 400 mm  
C2 = 200 mm  
C3 = 100 mm  
C4 = 1200 mm

### Thermal Protection Option

TR = Thermistor  
If No Thermal Protection. leave blank.

## Magnetic Way Ironless Types

**MW 030 - L - 0128**

### Magnet Way Type

MW = Ironless

### Magnet Way Width (mm)

030 = 30 mm  
050 = 50 mm  
075 = 75 mm  
100 = 100 mm

### Magnet Assembly Way Length (mm)

0064 = 64mm  
0128 = 128mm  
0256 = 256mm  
0512 = 512mm

L = Low Profile

(30 & 50 mm Ironless only)  
For standard assemblies leave blank.

## Hall Effect Assembly Ironless Types

**HDIL 100 XX**

### Hall Effect

HDIL = Digital for Ironless (Microswitch SS461A)

### Winding Code

100 (A1, A2, A3, A4)  
200 (A5, A6, A7, A8)

### Cable Option

Px - Cable with Connector:  
Configuration (P1) includes 400 mm shielded cable with connector (lengths as above)  
Cx - flying leads (lengths as above)



## About Kollmorgen

Kollmorgen is a leading provider of motion systems and components for machine builders. Through world-class knowledge in motion, industry-leading quality and deep expertise in linking and integrating standard and custom products, Kollmorgen delivers breakthrough solutions that are unmatched in performance, reliability and ease-of-use, giving machine builders an irrefutable marketplace advantage.

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